

# Stochastic Differential Equations

## in NONMEM:

### A diagnostic tool for pinpointing model deficiencies

Christoffer W. Tornøe<sup>1,2,3</sup>, Henrik Agersø<sup>1</sup>, Rune V. Overgaard<sup>2</sup>,  
Henrik A. Nielsen<sup>2</sup>, Henrik Madsen<sup>2</sup>, and E. Niclas Jonsson<sup>3</sup>

<sup>1</sup>Experimental Medicine, Ferring Pharmaceuticals A/S

<sup>2</sup>Informatics and Mathematical Modelling, Technical University of Denmark

<sup>3</sup>Division of Pharmacokinetics and Drug Therapy, Uppsala University

ECPAG Meeting, April 27<sup>th</sup>, 2004



# Outline of Presentation

- Aims of analysis
- Motivation
- Methods
  - Stochastic differential equations
  - Extended Kalman Filter
- Results
  - PK/PD of GnRH antagonist degarelix
  - Framework for pinpointing model deficiencies
- Conclusions

# Aims of analysis

- Introduce stochastic differential equations (SDEs) to PK/PD modelling.
- Illustrate the Extended Kalman Filter for parameter estimation in SDEs
- Application to PK/PD data of GnRH antagonist degarelix for tracking of parameters and deconvolution of effect model.

# Motivation

- Why use stochastic instead of ordinary differential equations ?

# Motivation

- Why use stochastic instead of ordinary differential equations ?
- When auto-correlated residual errors are observed due to structural model misspecifications or true physiological variations.

# Motivation

- Why use stochastic instead of ordinary differential equations ?
  - When auto-correlated residual errors are observed due to structural model misspecifications or true physiological variations.
  - Decomposes the residual error into system and measurement noise.

# Motivation

- Why use stochastic instead of ordinary differential equations ?
  - When auto-correlated residual errors are observed due to structural model misspecifications or true physiological variations.
  - Decomposes the residual error into system and measurement noise.
  - Can be used as a diagnostic tool for model appropriateness.

# Motivation

- Why use stochastic instead of ordinary differential equations ?
  - When auto-correlated residual errors are observed due to structural model misspecifications or true physiological variations.
  - Decomposes the residual error into system and measurement noise.
  - Can be used as a diagnostic tool for model appropriateness.
  - Provides a framework for pinpointing model deficiencies.



# Methods

- Ordinary differential equations

$$d\mathbf{A}/dt = g(\boldsymbol{\theta}, \mathbf{A}, d)$$

$$\mathbf{y}_k = \mathbf{f}(\boldsymbol{\theta}, \mathbf{A}) + \boldsymbol{\epsilon}_k$$

# Methods

- Ordinary differential equations

$$d\mathbf{A}/dt = g(\boldsymbol{\theta}, \mathbf{A}, d)$$

$$\mathbf{y}_k = f(\boldsymbol{\theta}, \mathbf{A}) + \boldsymbol{\epsilon}_k$$

- Stochastic differential equations

$$d\mathbf{A} = g(\boldsymbol{\theta}, \mathbf{A}, d) dt + \boldsymbol{\sigma}_w d\mathbf{w}_t$$

$$\mathbf{y}_k = f(\boldsymbol{\theta}, \mathbf{A}) + \boldsymbol{\epsilon}_k$$

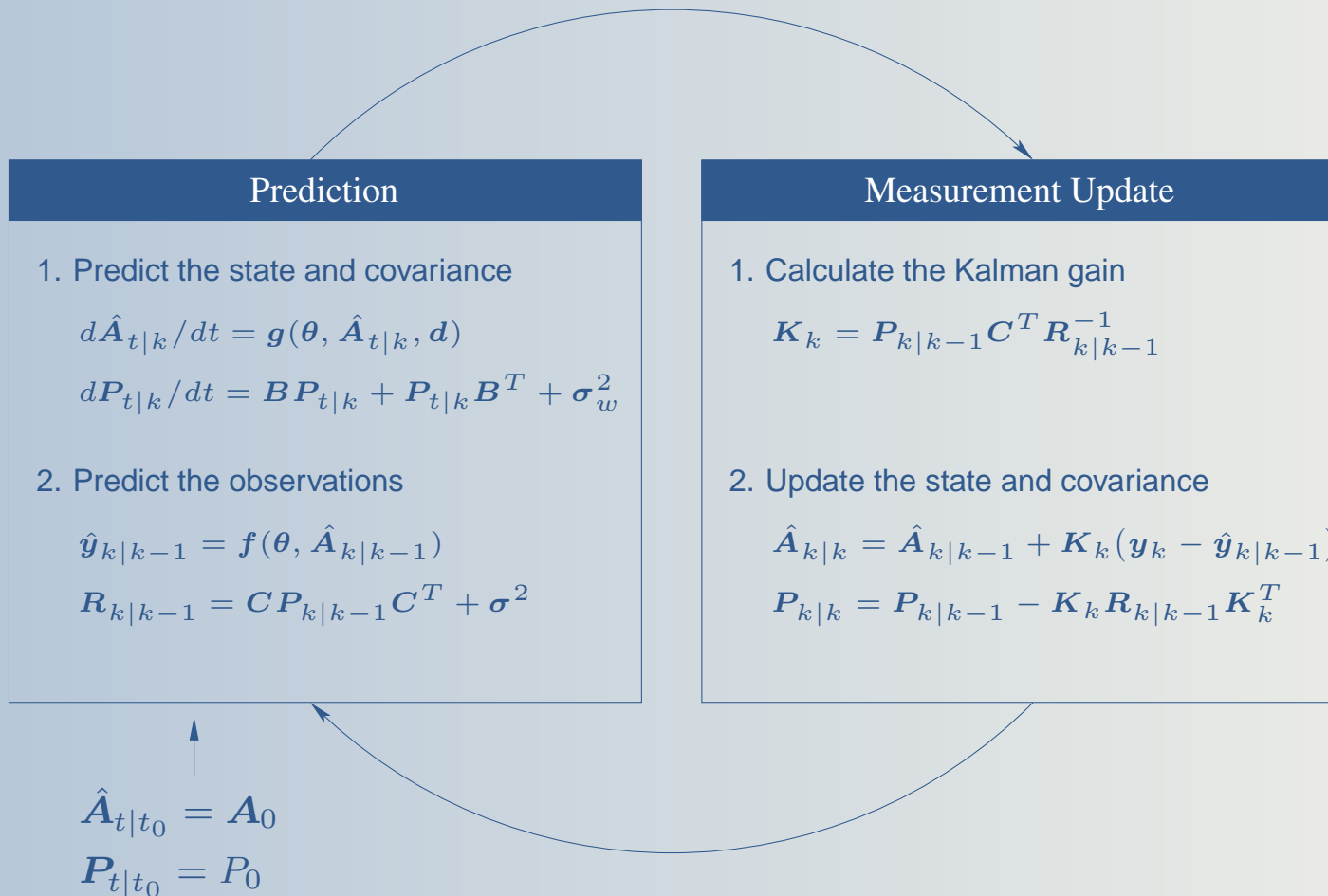
# Methods

## Extended Kalman Filter

$$d\mathbf{A} = \mathbf{g}(\boldsymbol{\theta}, \mathbf{A}, \mathbf{d}) dt + \boldsymbol{\sigma}_w d\mathbf{w}_t$$

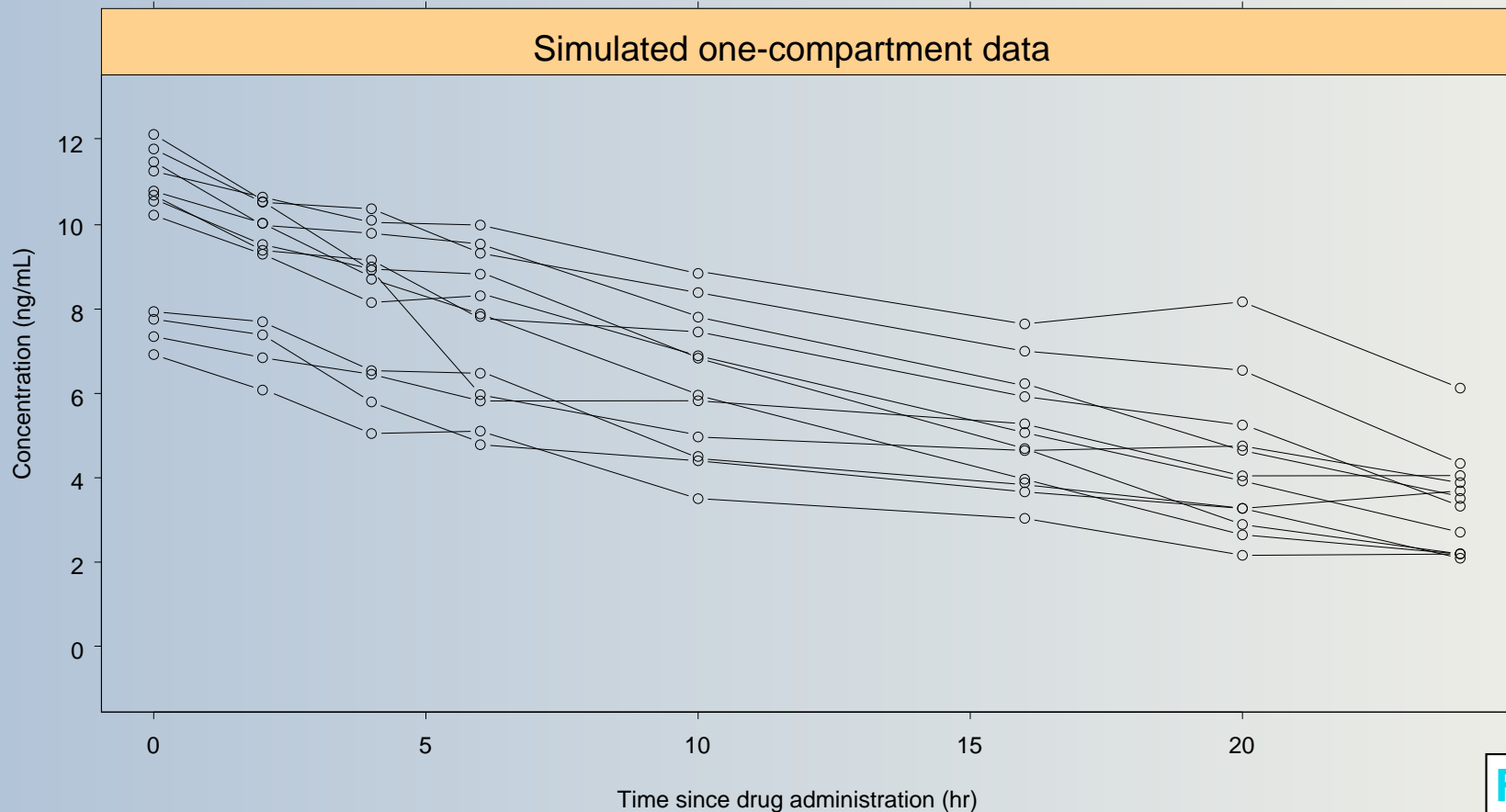
$$\mathbf{y}_k = \mathbf{f}(\boldsymbol{\theta}, \mathbf{A}) + \boldsymbol{\epsilon}_k$$

$$\mathbf{B} = \left. \frac{\partial \mathbf{g}}{\partial \mathbf{A}} \right|_{\mathbf{A}=\hat{\mathbf{A}}} \quad \mathbf{C} = \left. \frac{\partial \mathbf{f}}{\partial \mathbf{A}} \right|_{\mathbf{A}=\hat{\mathbf{A}}_{k|k-1}}$$



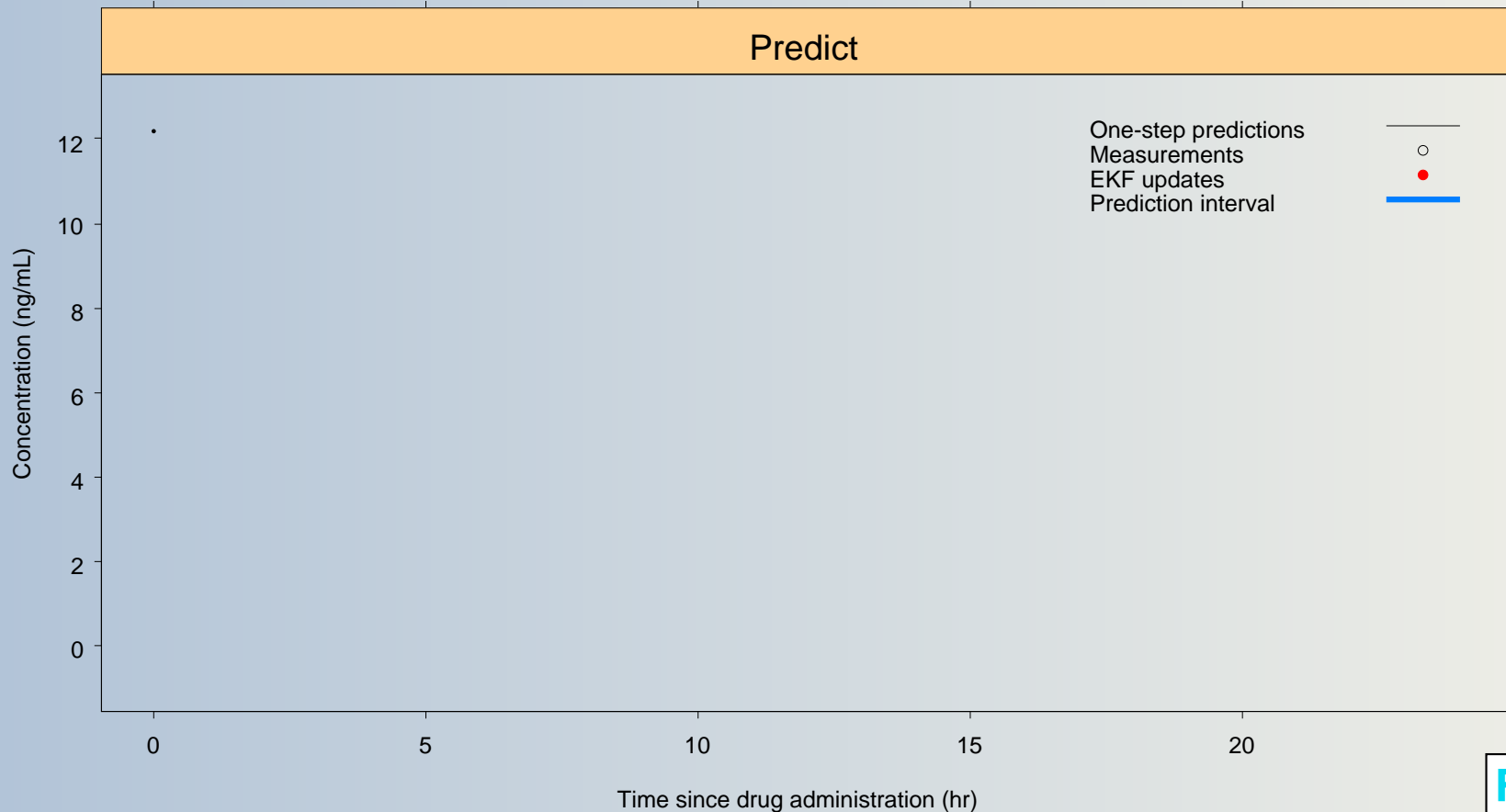
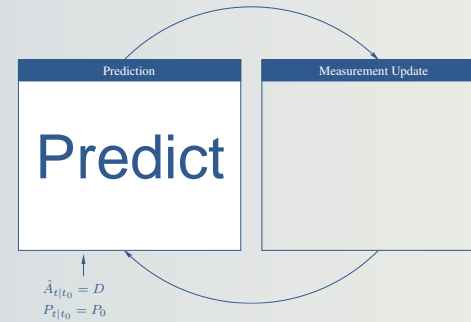
# Methods

## Extended Kalman Filter



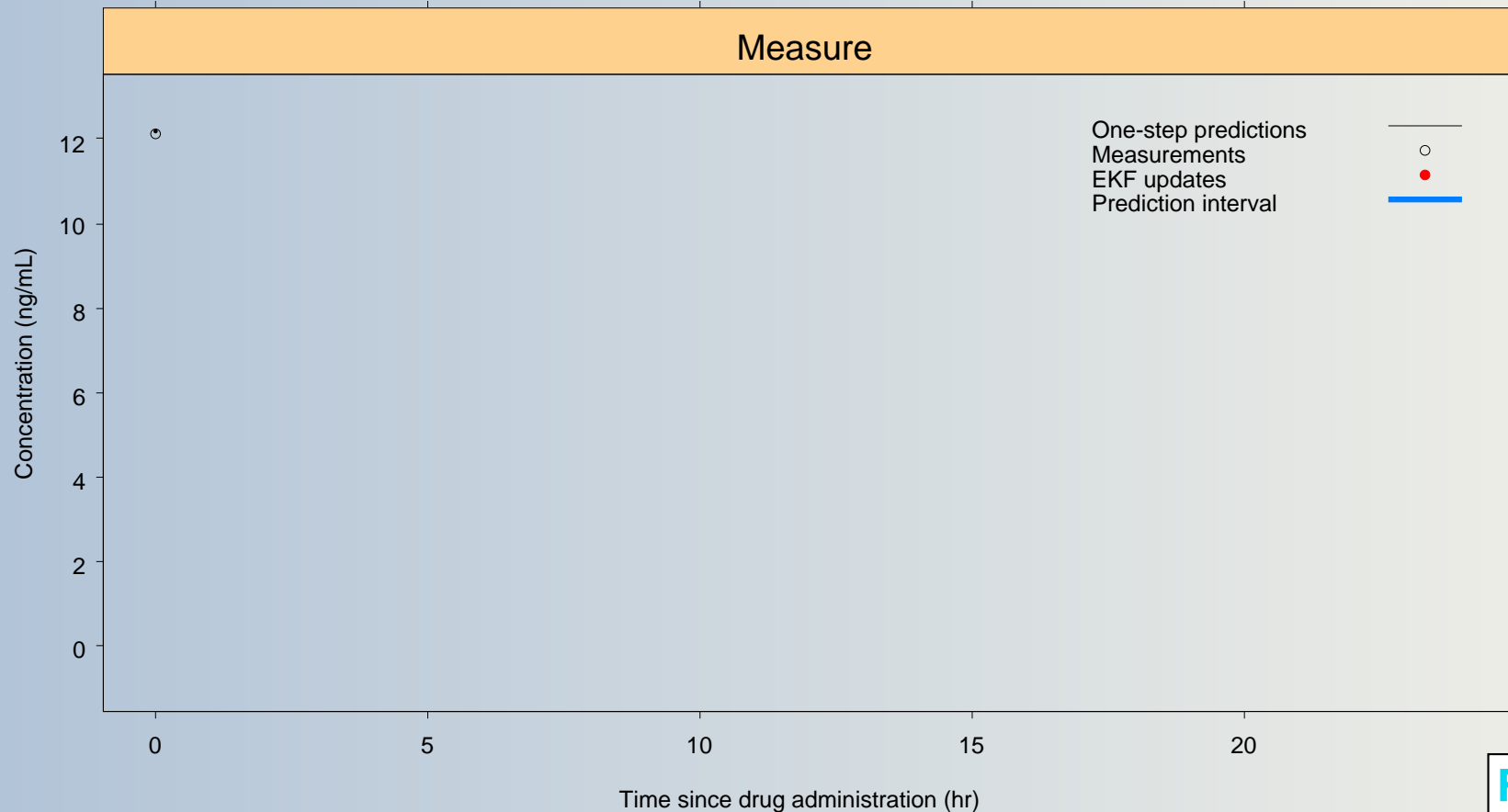
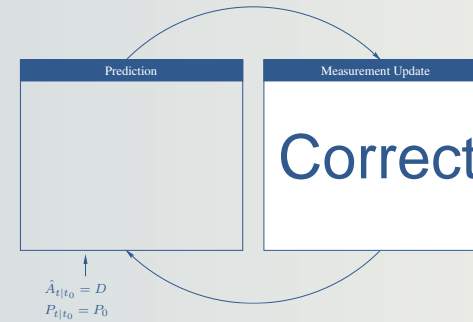
# Methods

## Extended Kalman Filter



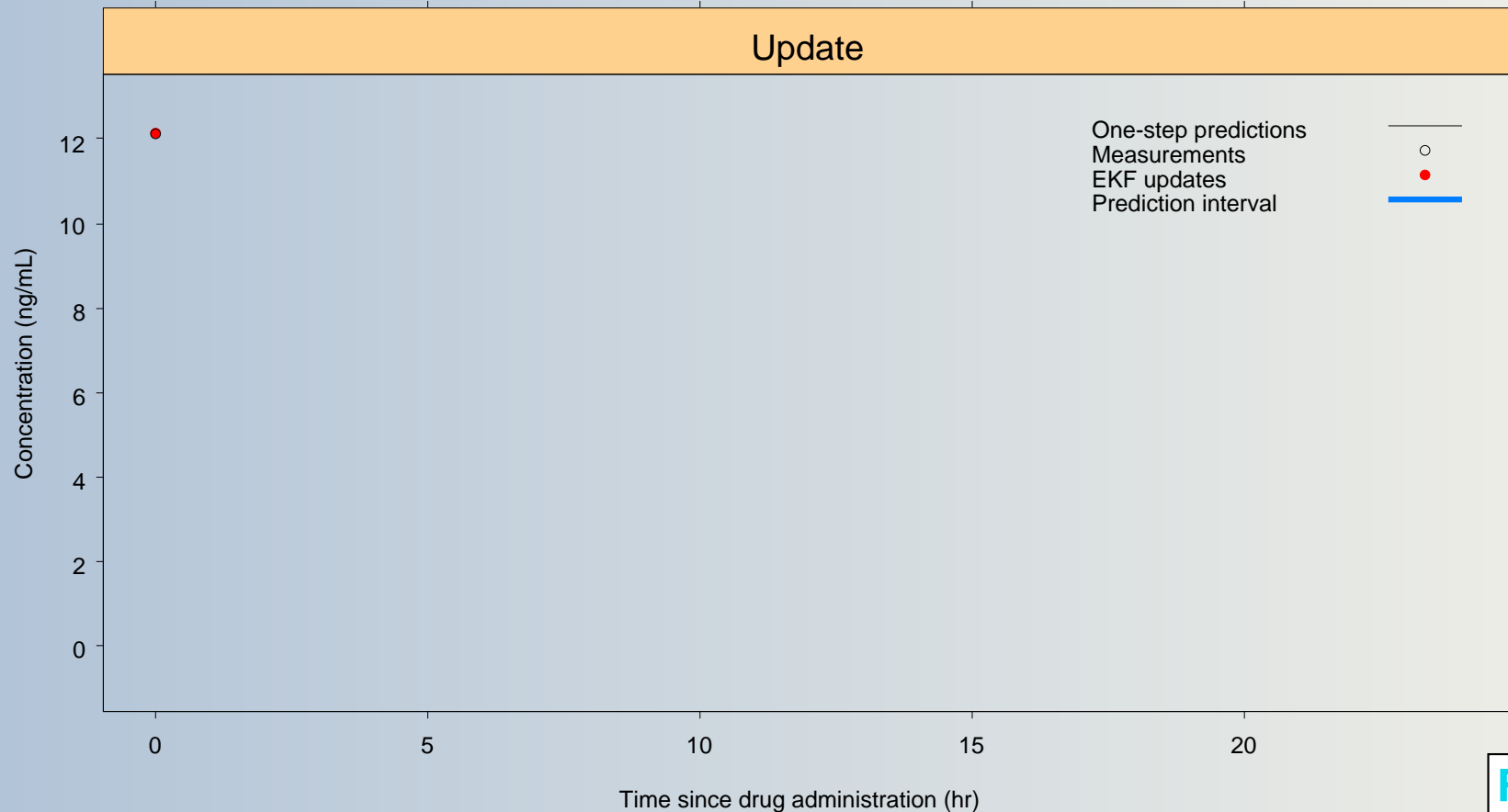
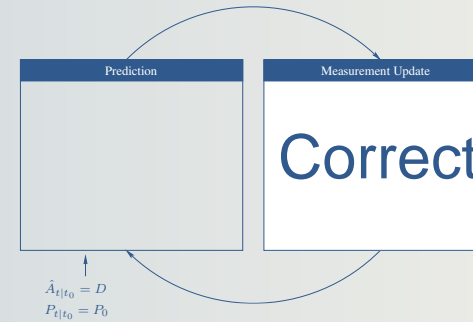
# Methods

## Extended Kalman Filter



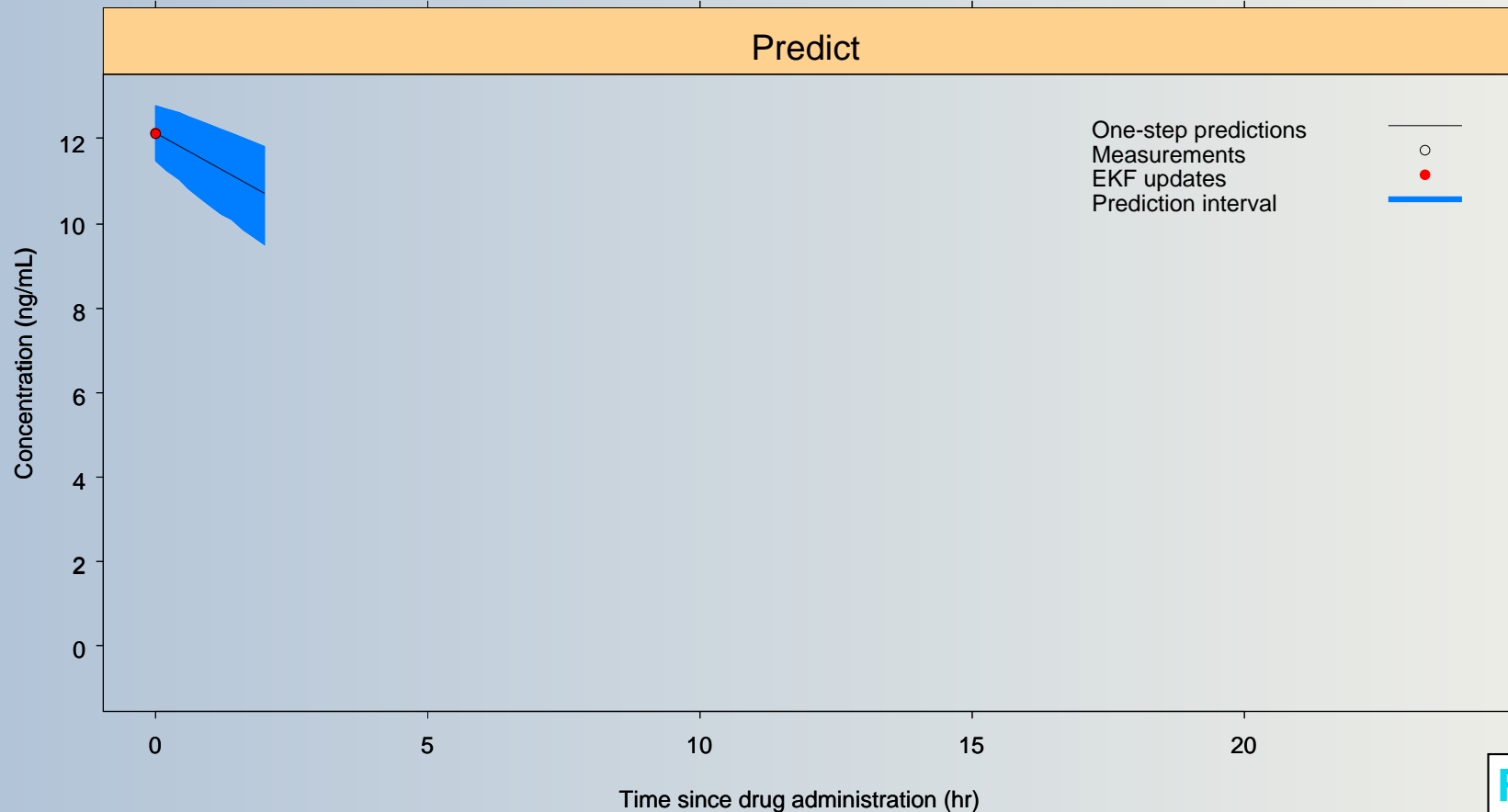
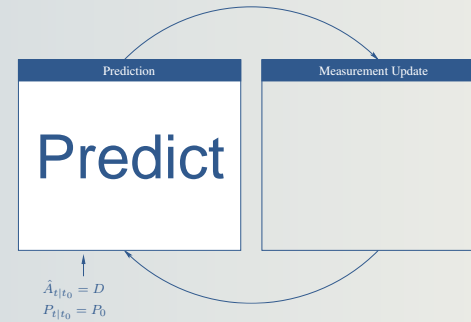
# Methods

## Extended Kalman Filter



# Methods

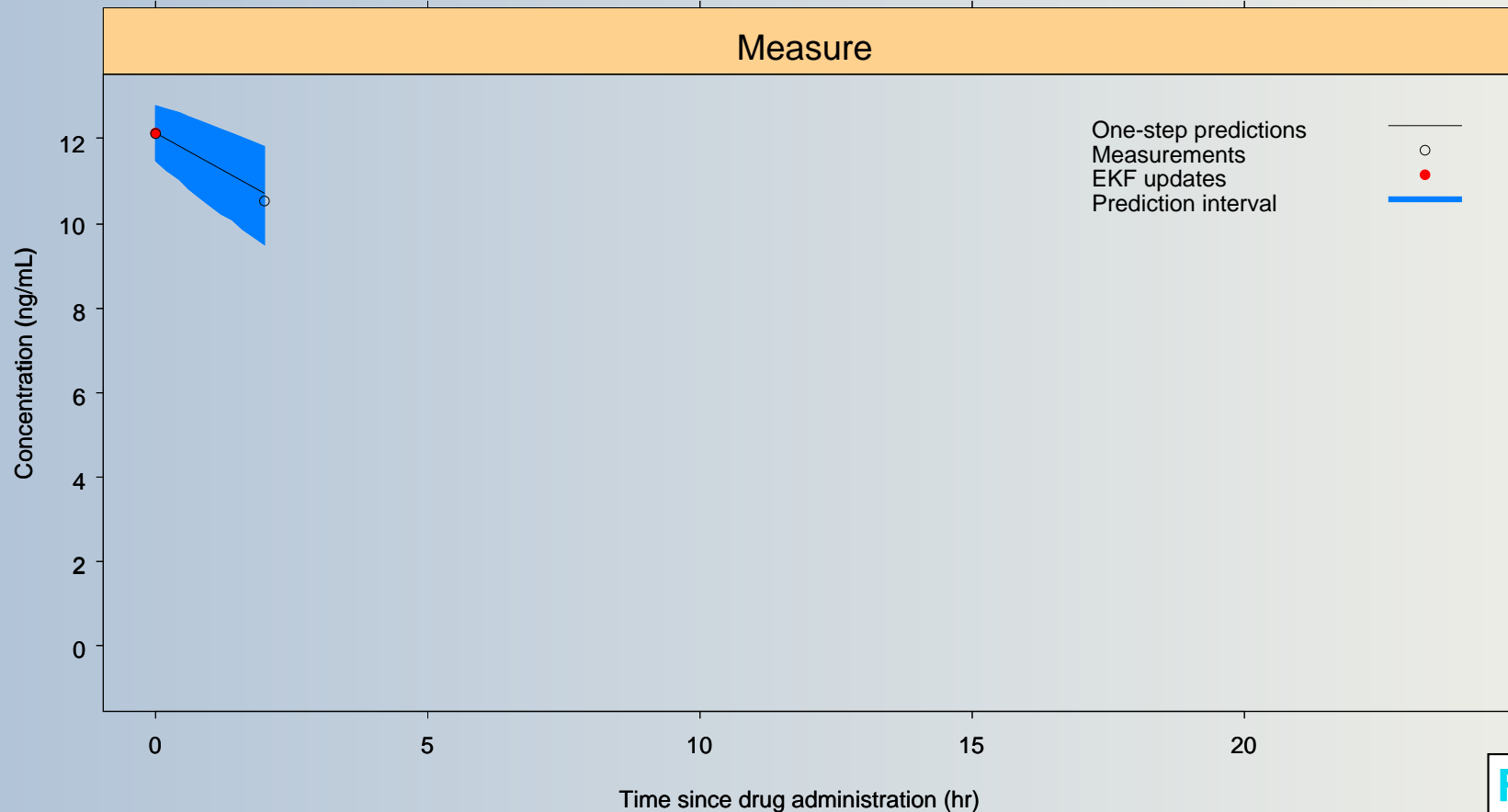
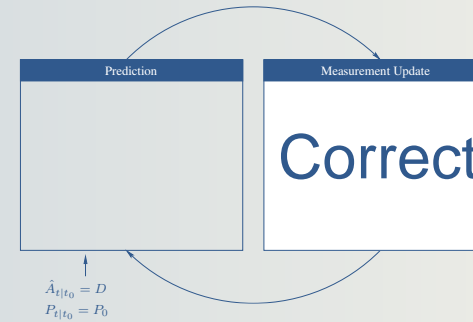
## Extended Kalman Filter





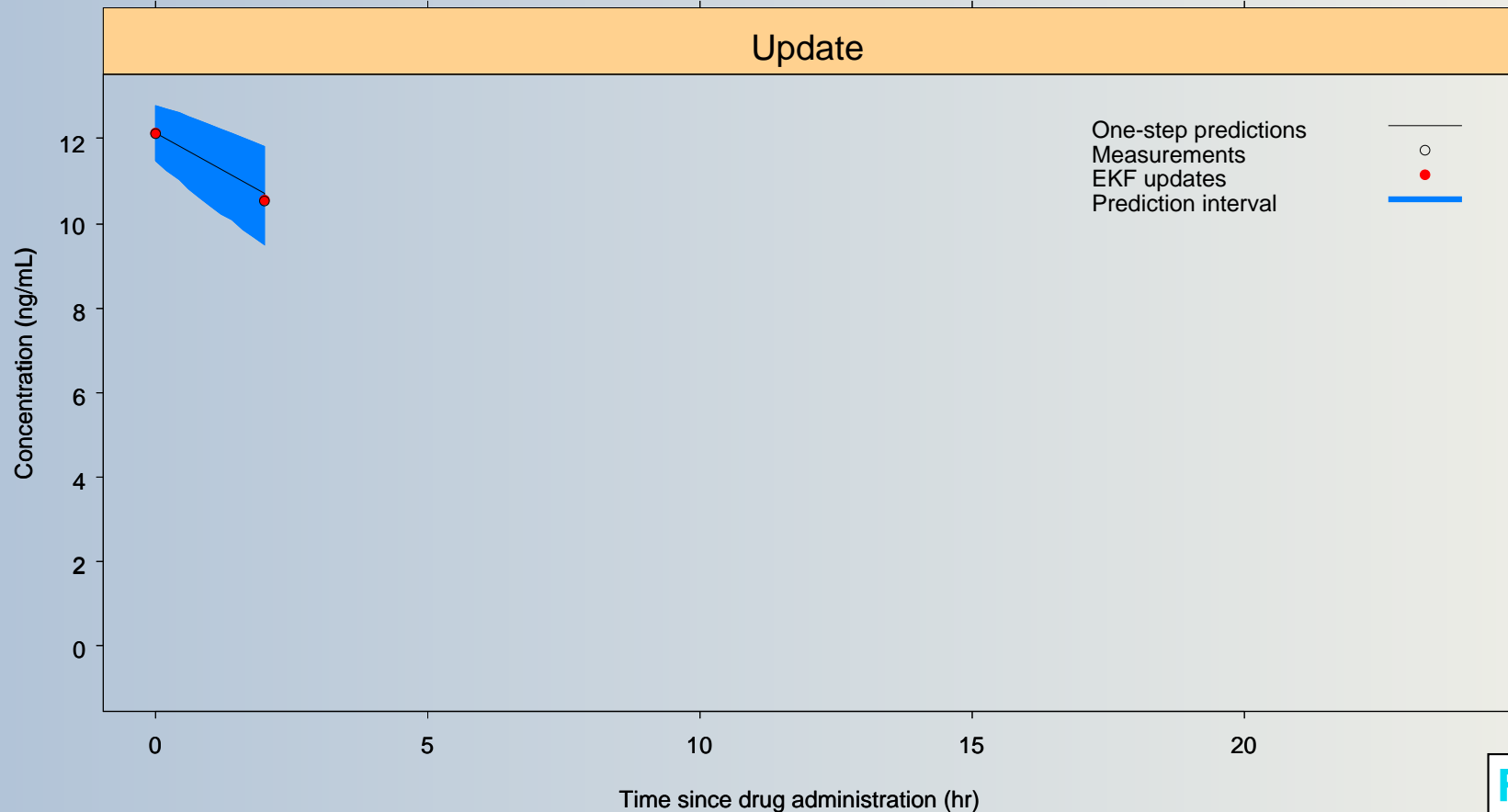
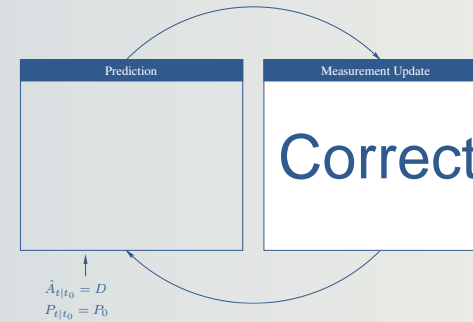
# Methods

## Extended Kalman Filter



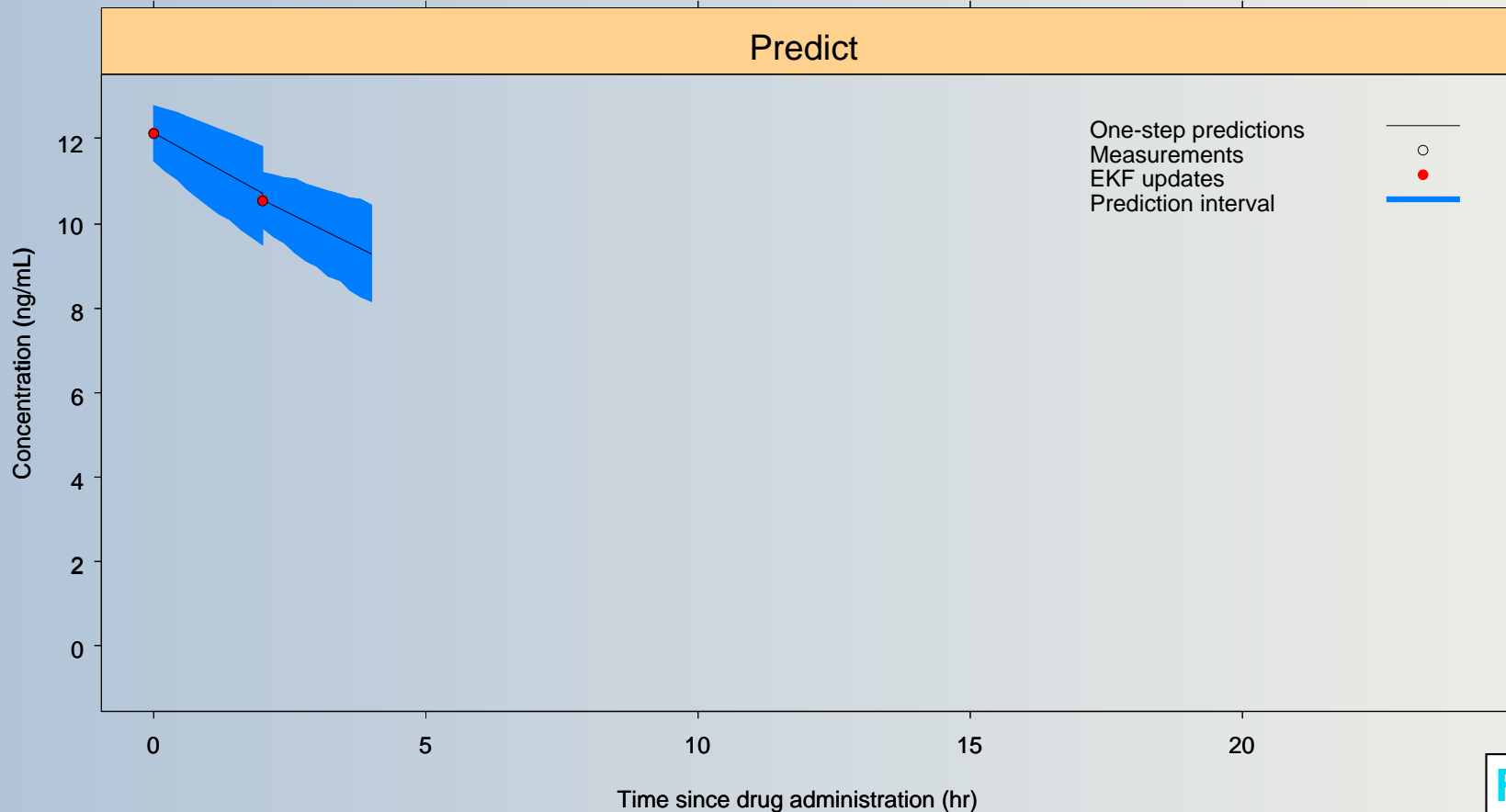
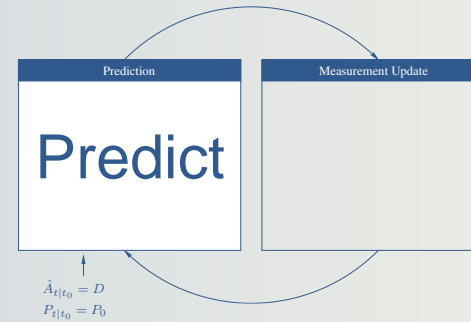
# Methods

## Extended Kalman Filter



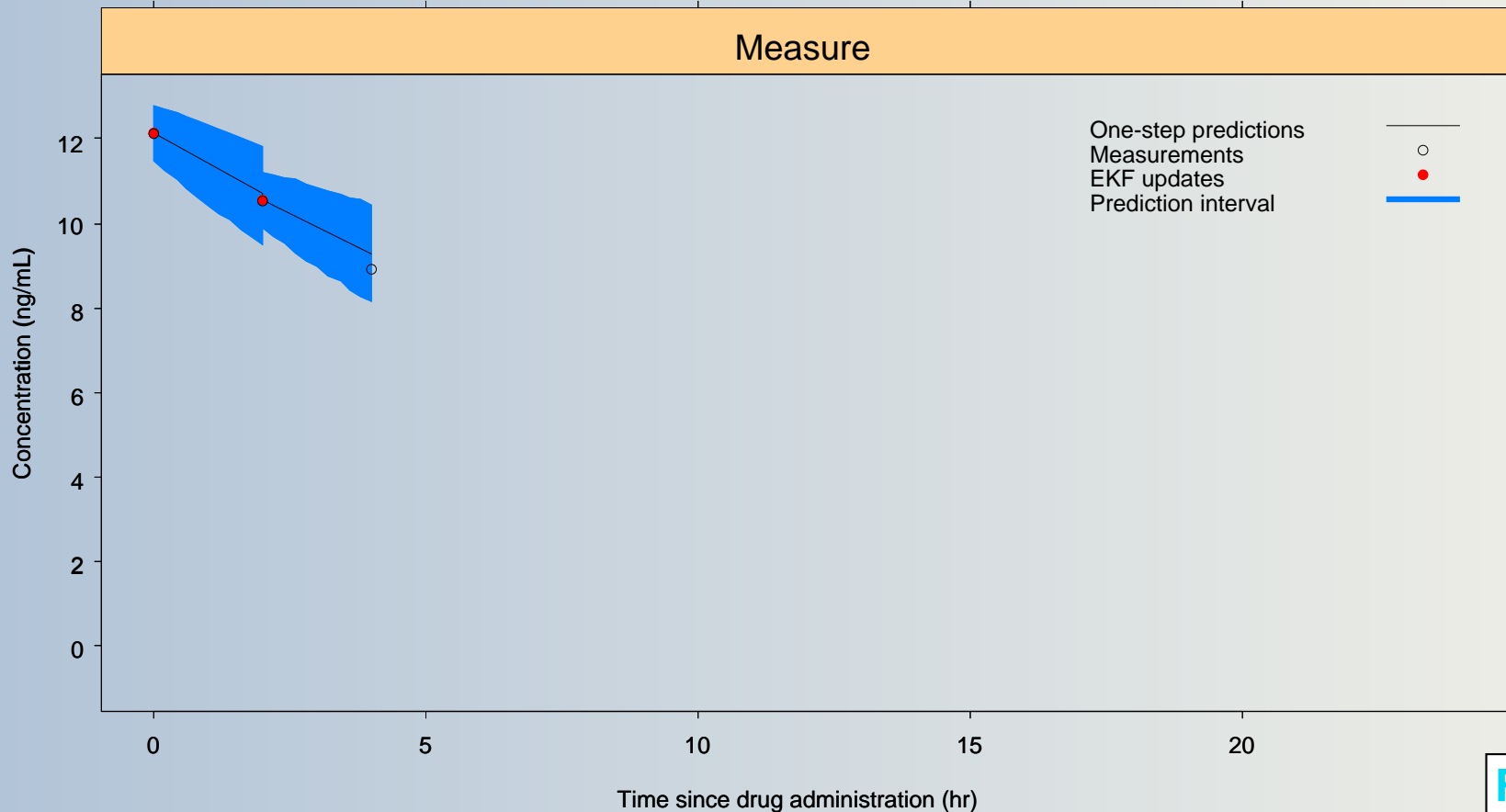
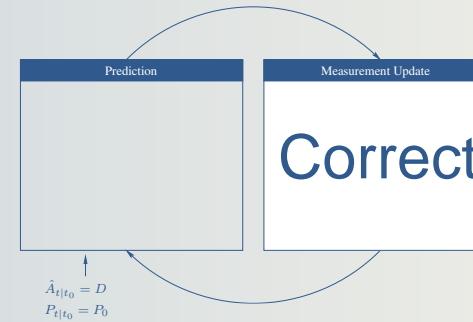
# Methods

## Extended Kalman Filter



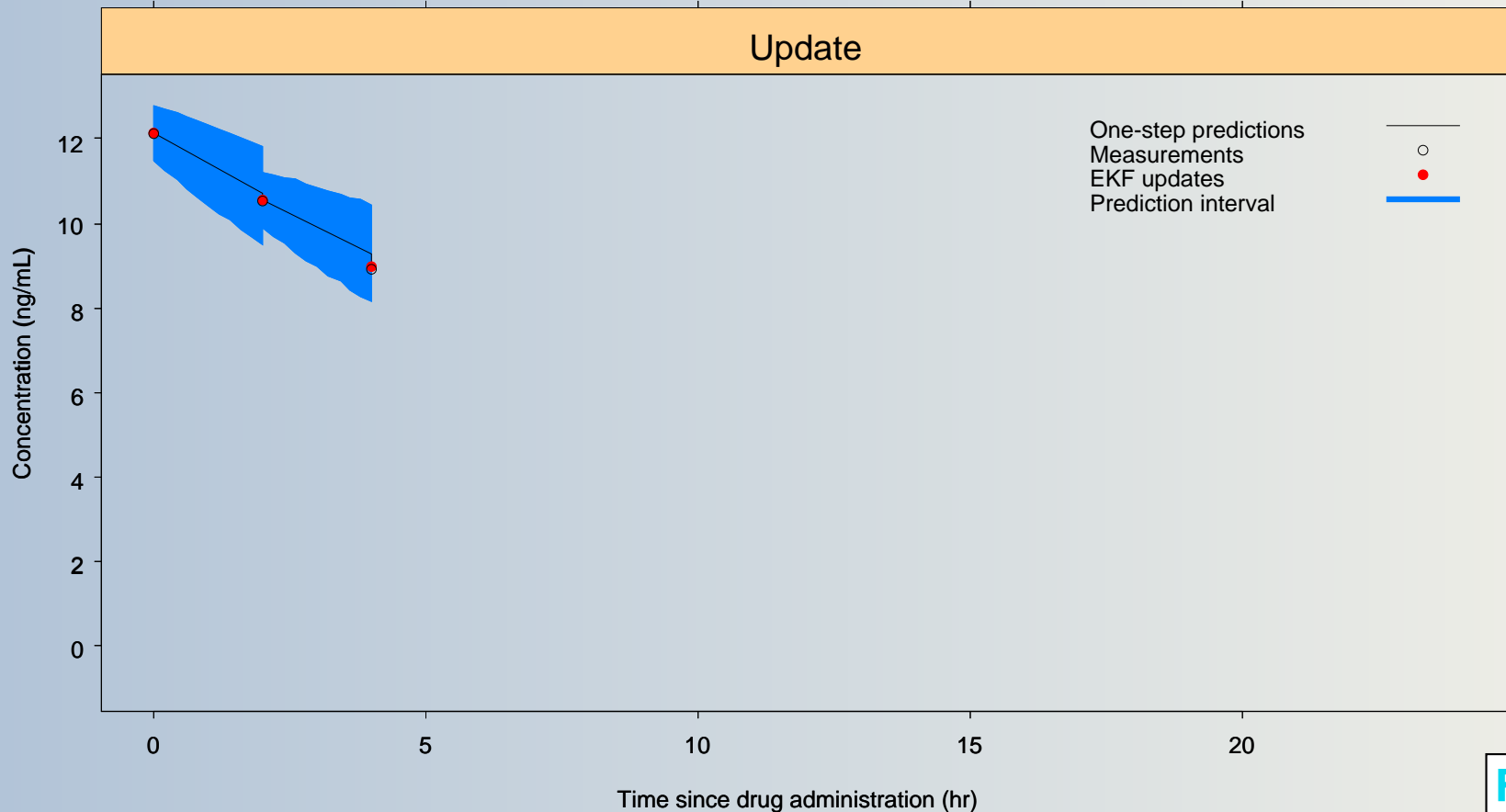
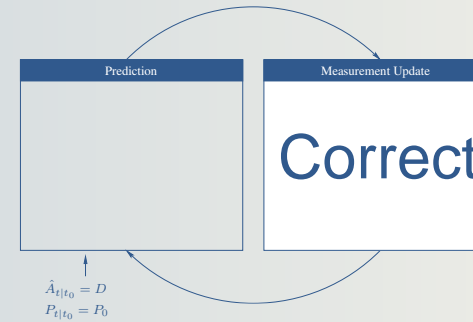
# Methods

## Extended Kalman Filter



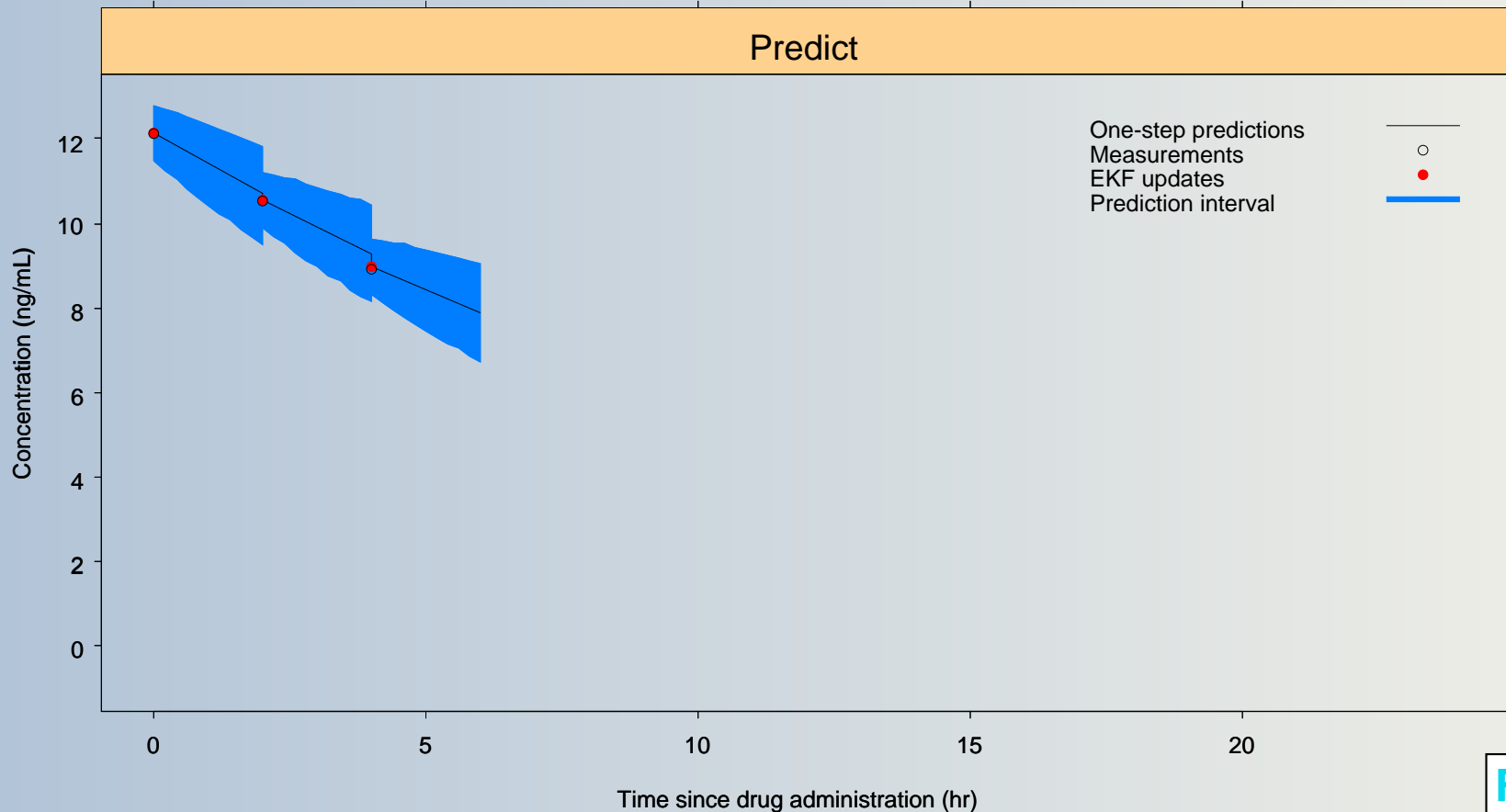
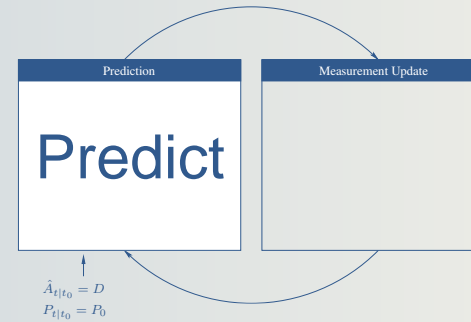
# Methods

## Extended Kalman Filter



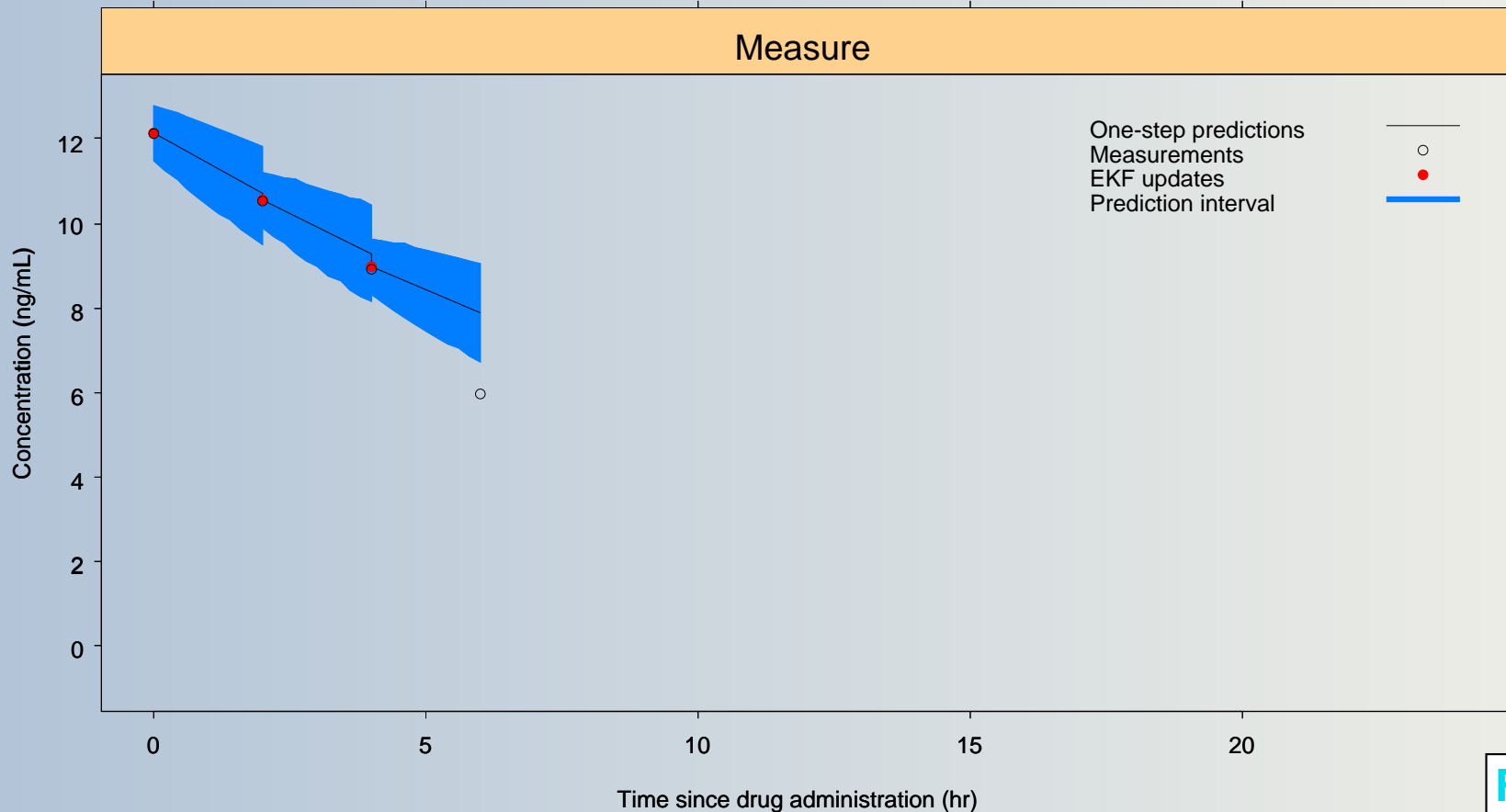
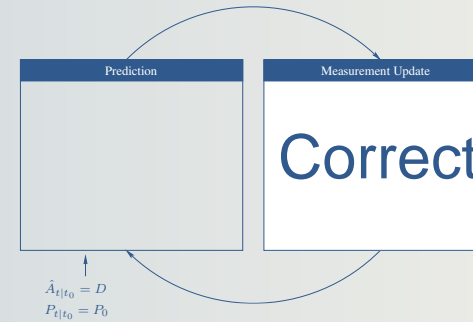
# Methods

## Extended Kalman Filter



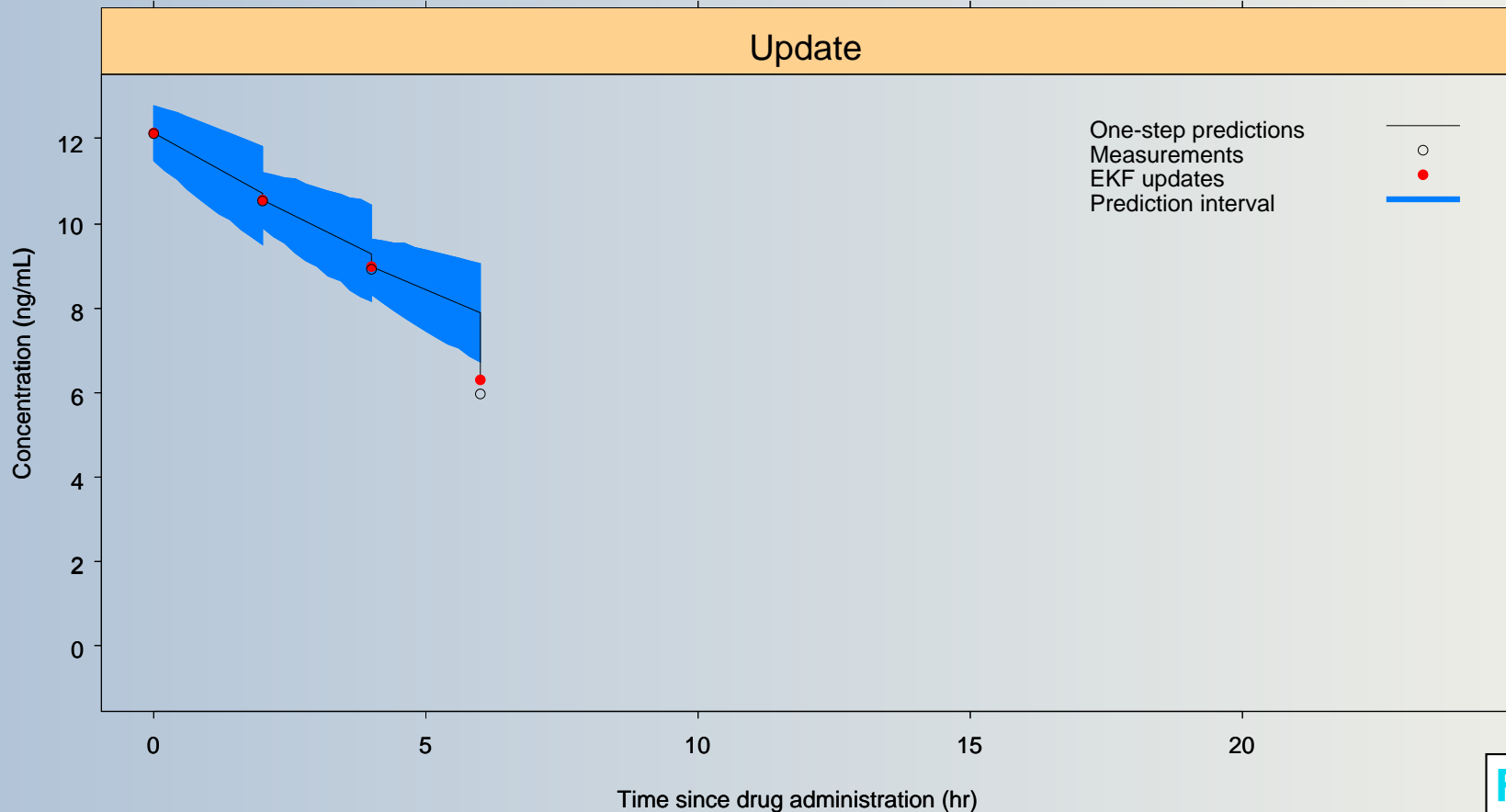
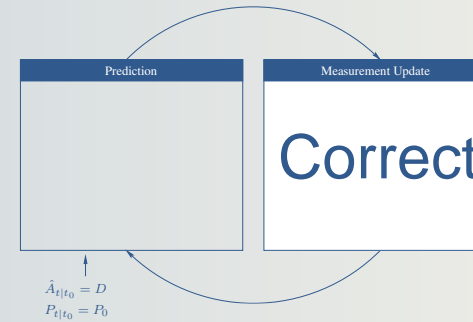
# Methods

## Extended Kalman Filter



# Methods

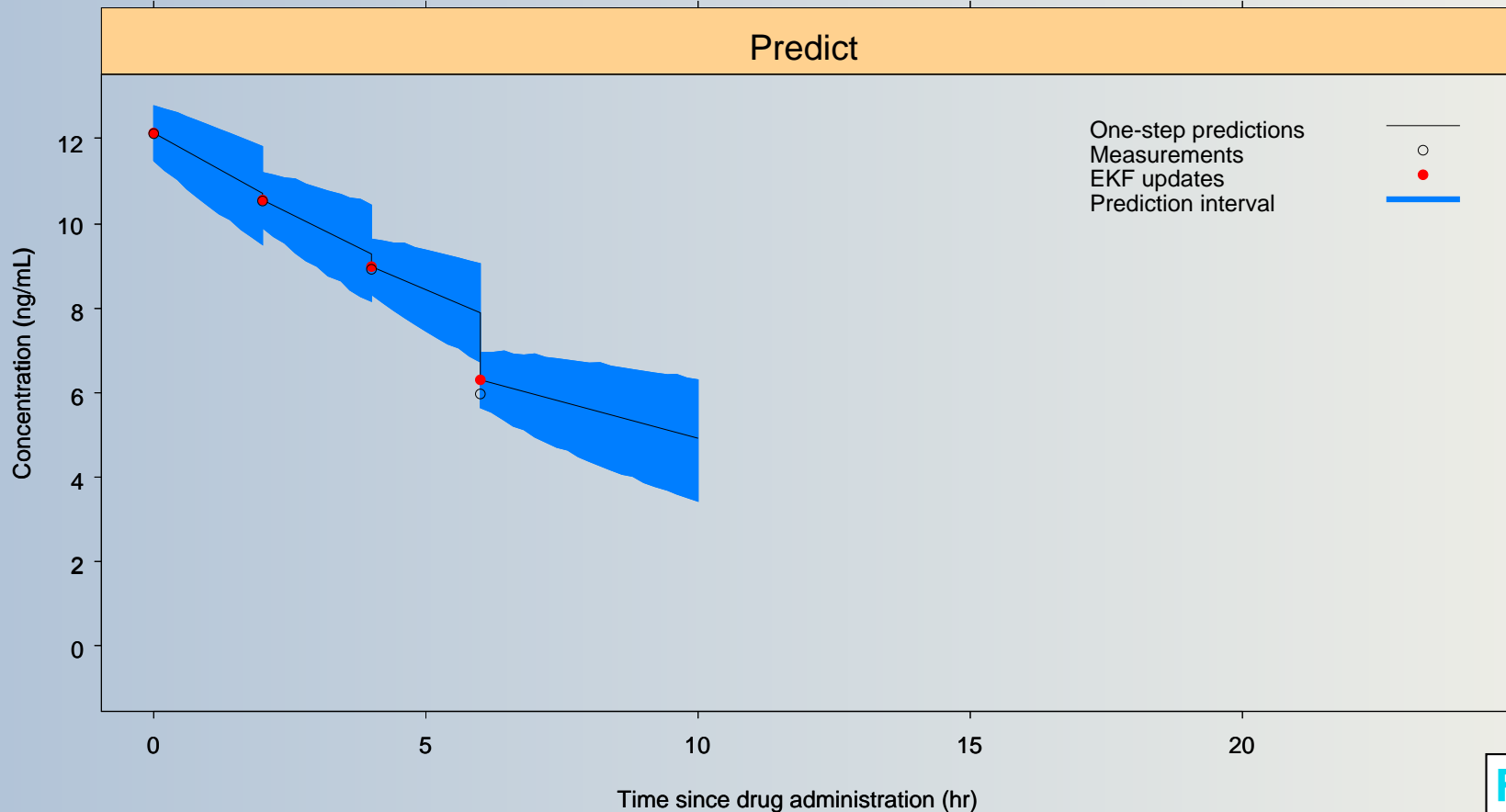
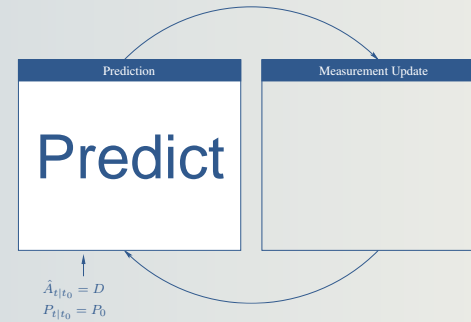
## Extended Kalman Filter





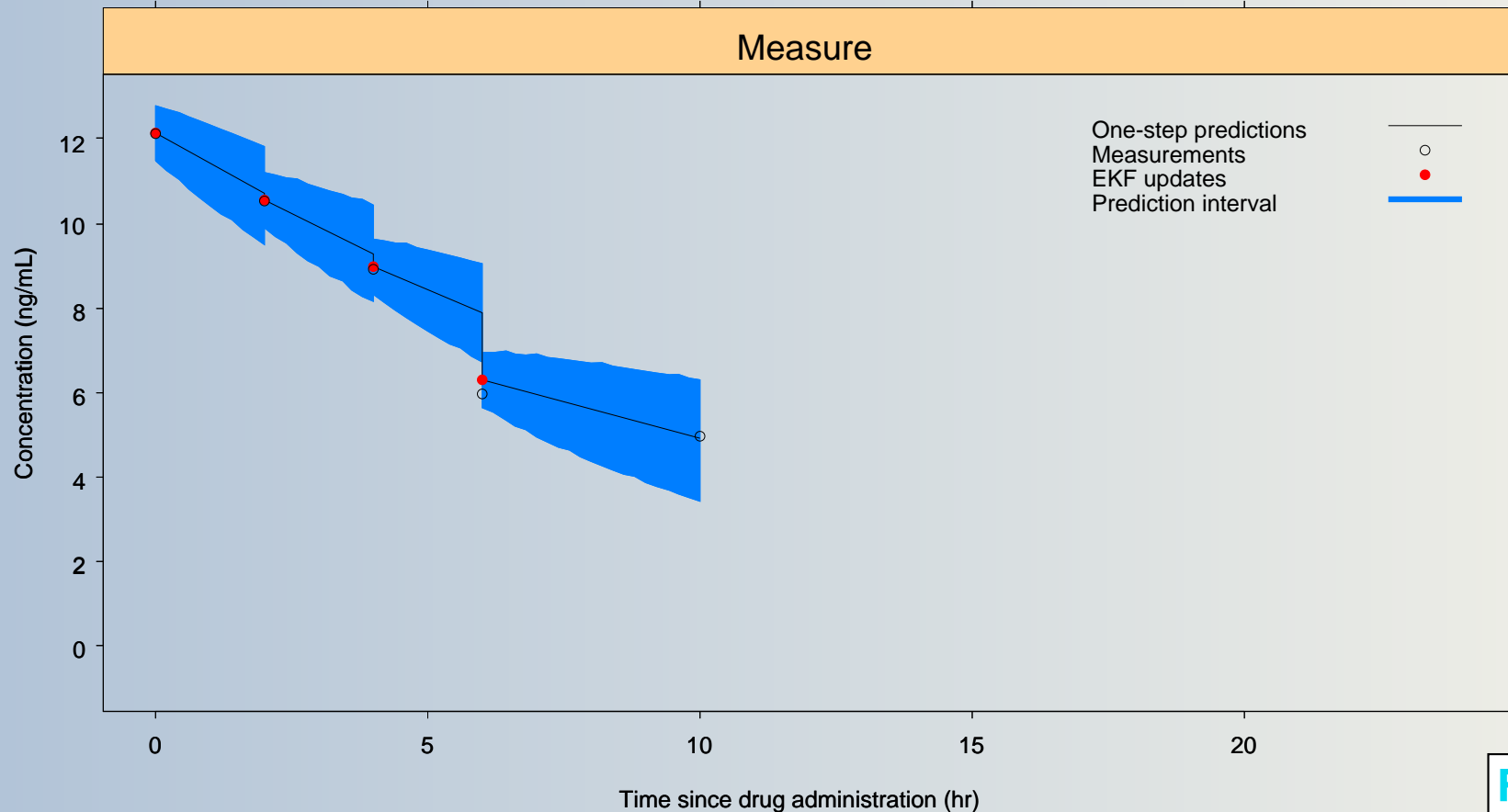
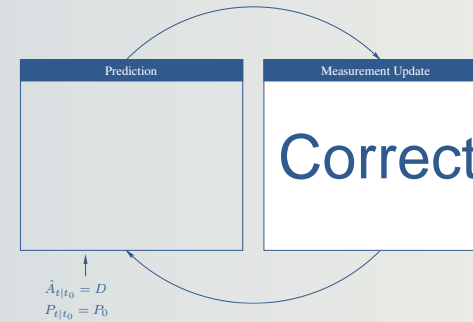
# Methods

## Extended Kalman Filter



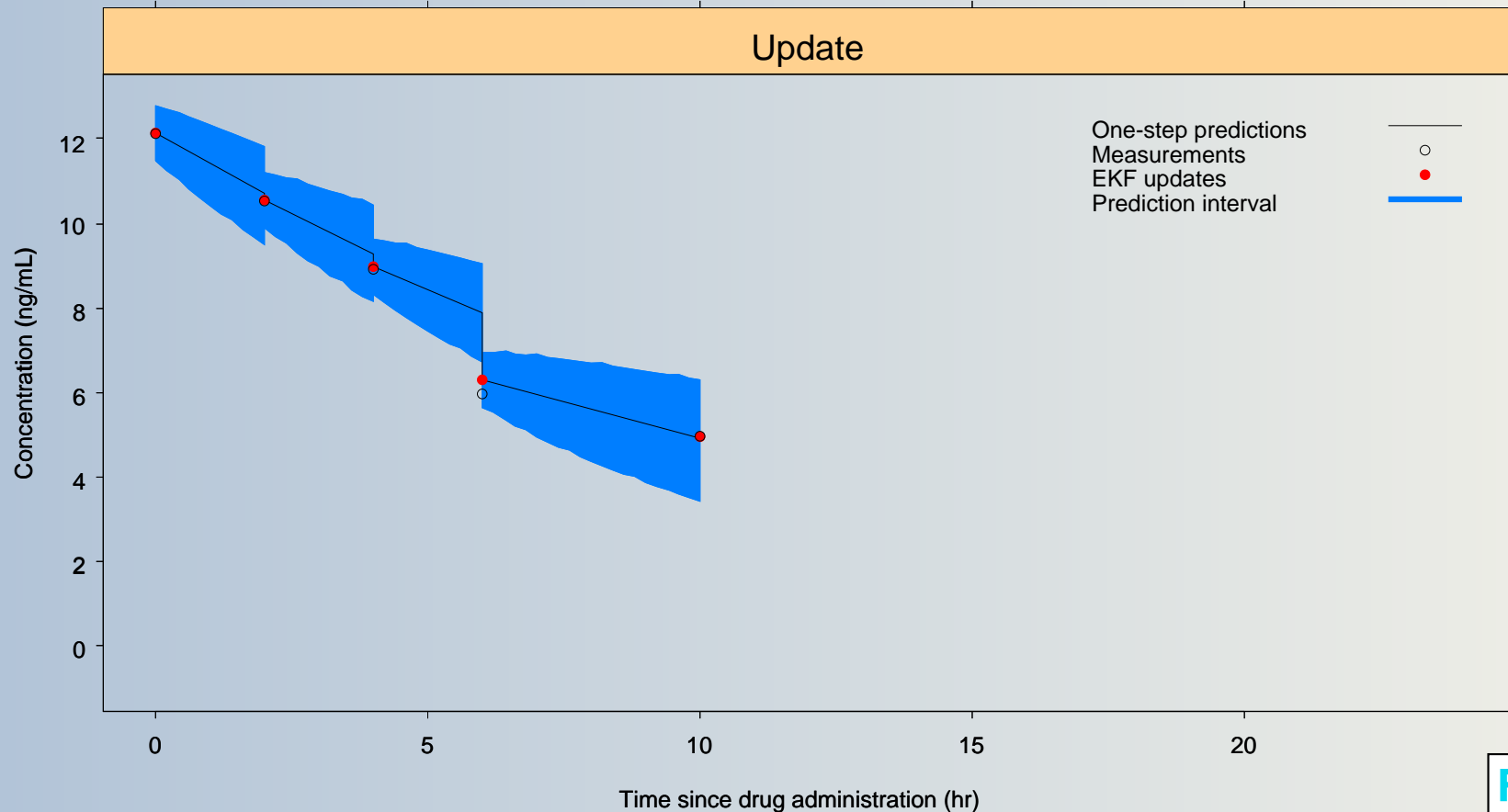
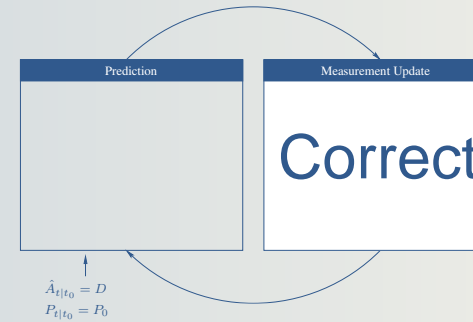
# Methods

## Extended Kalman Filter



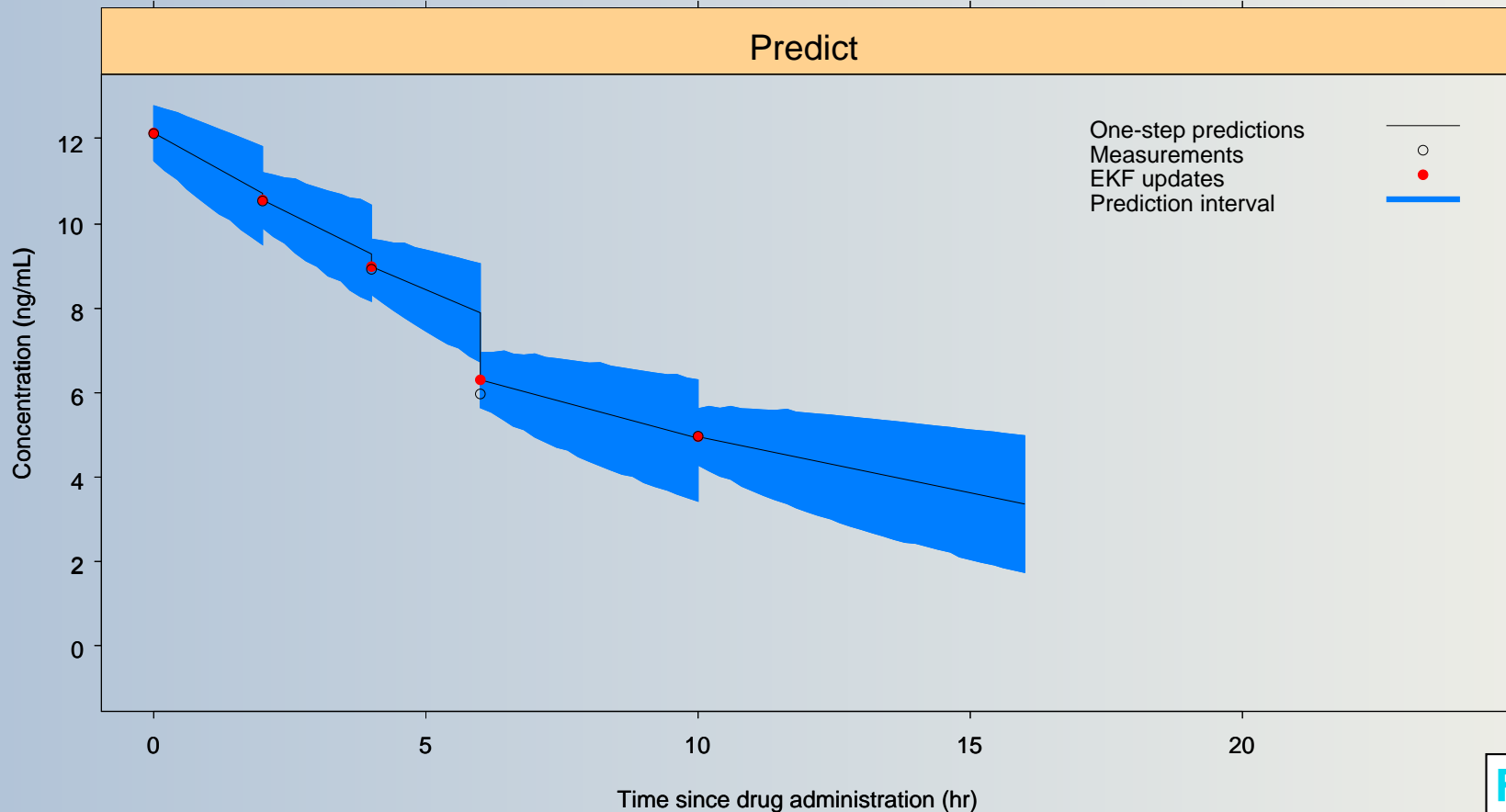
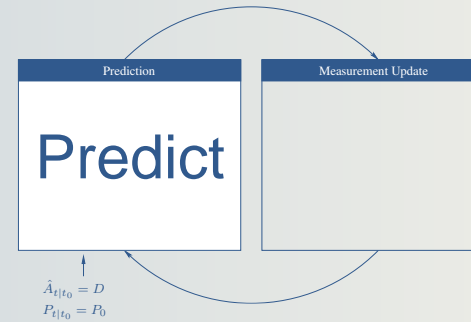
# Methods

## Extended Kalman Filter



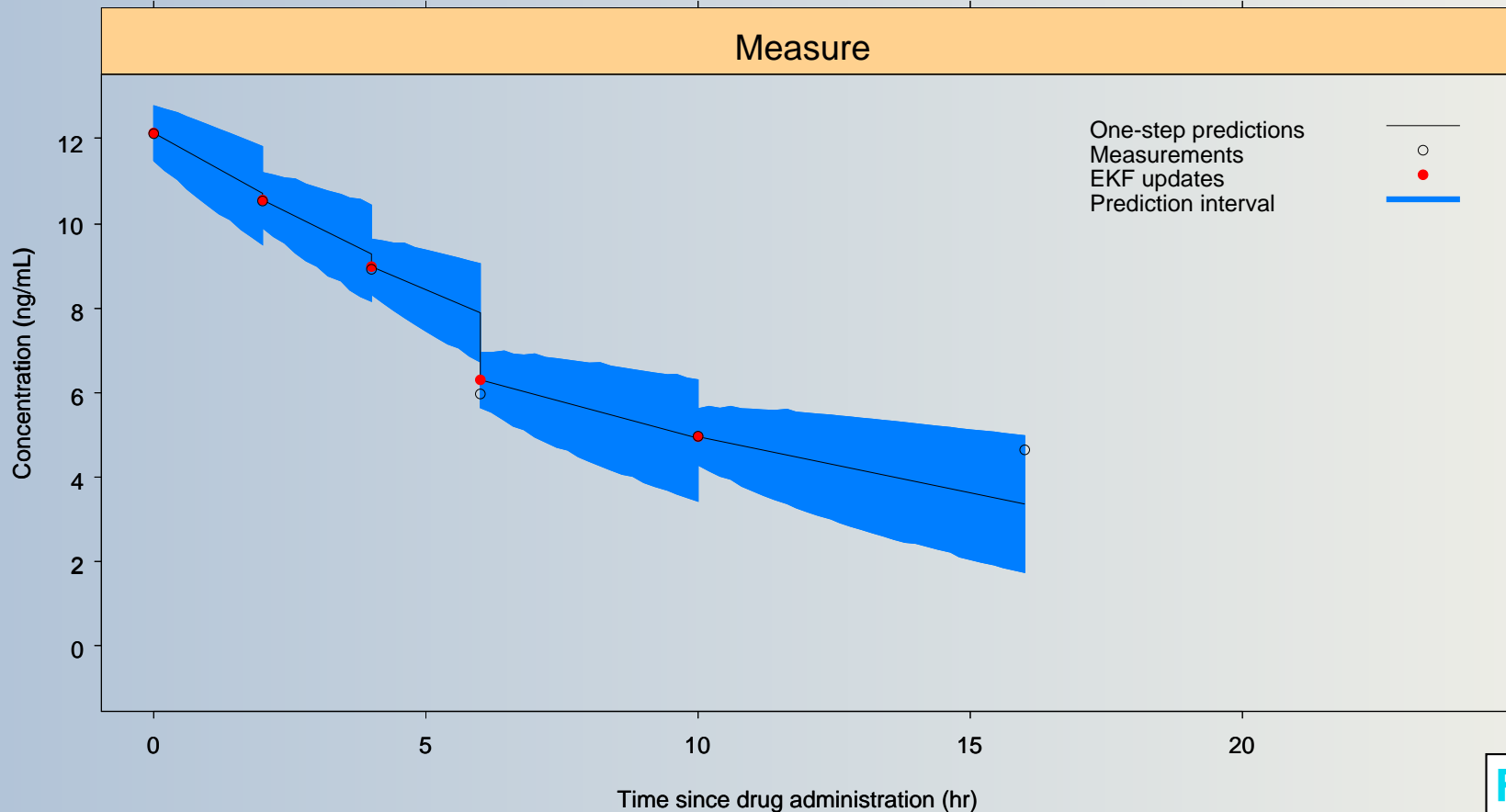
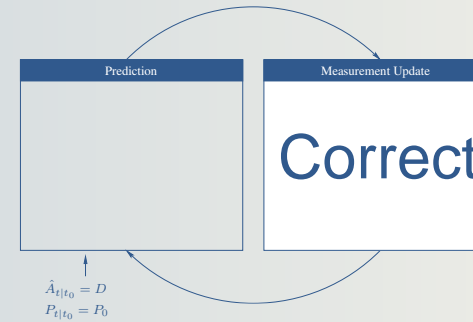
# Methods

## Extended Kalman Filter



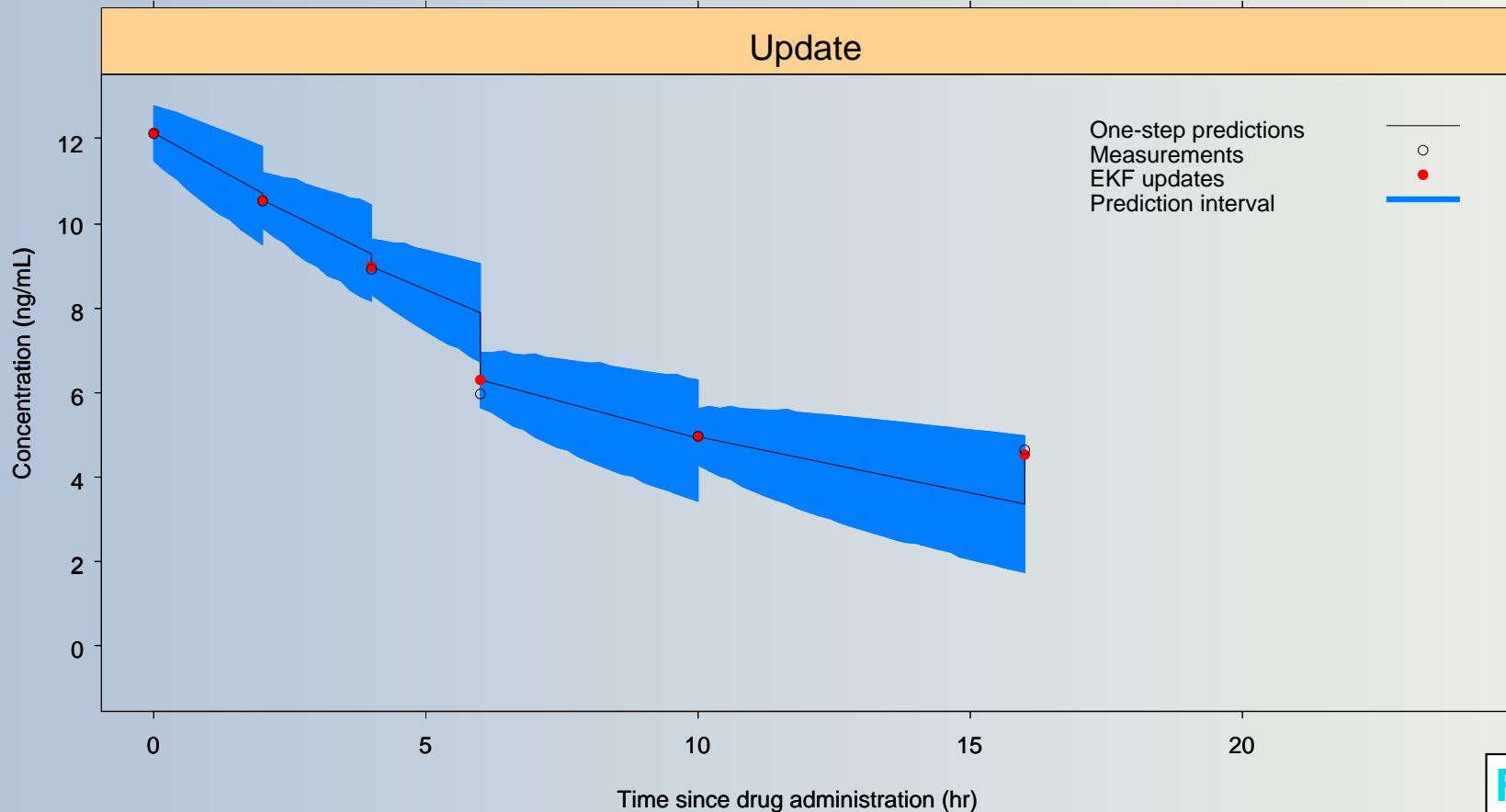
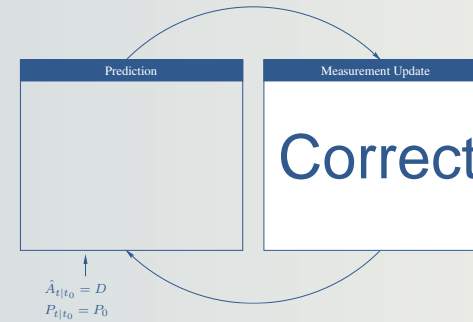
# Methods

## Extended Kalman Filter



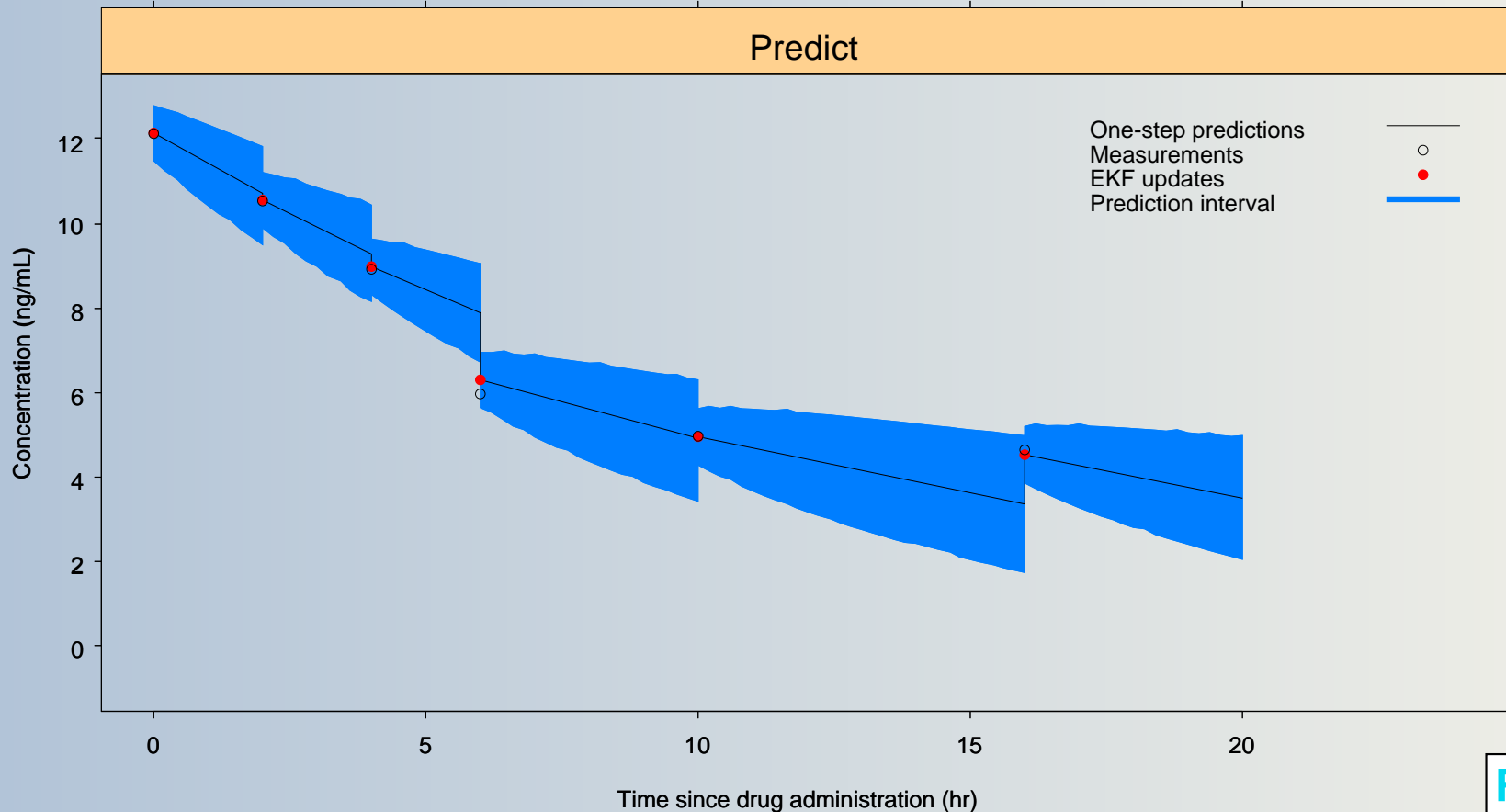
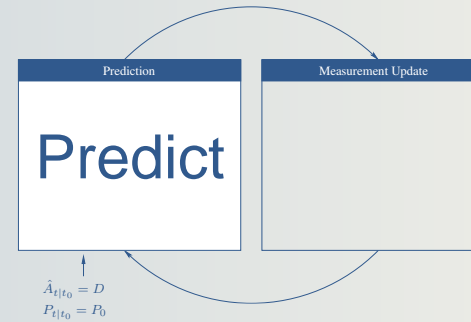
# Methods

## Extended Kalman Filter



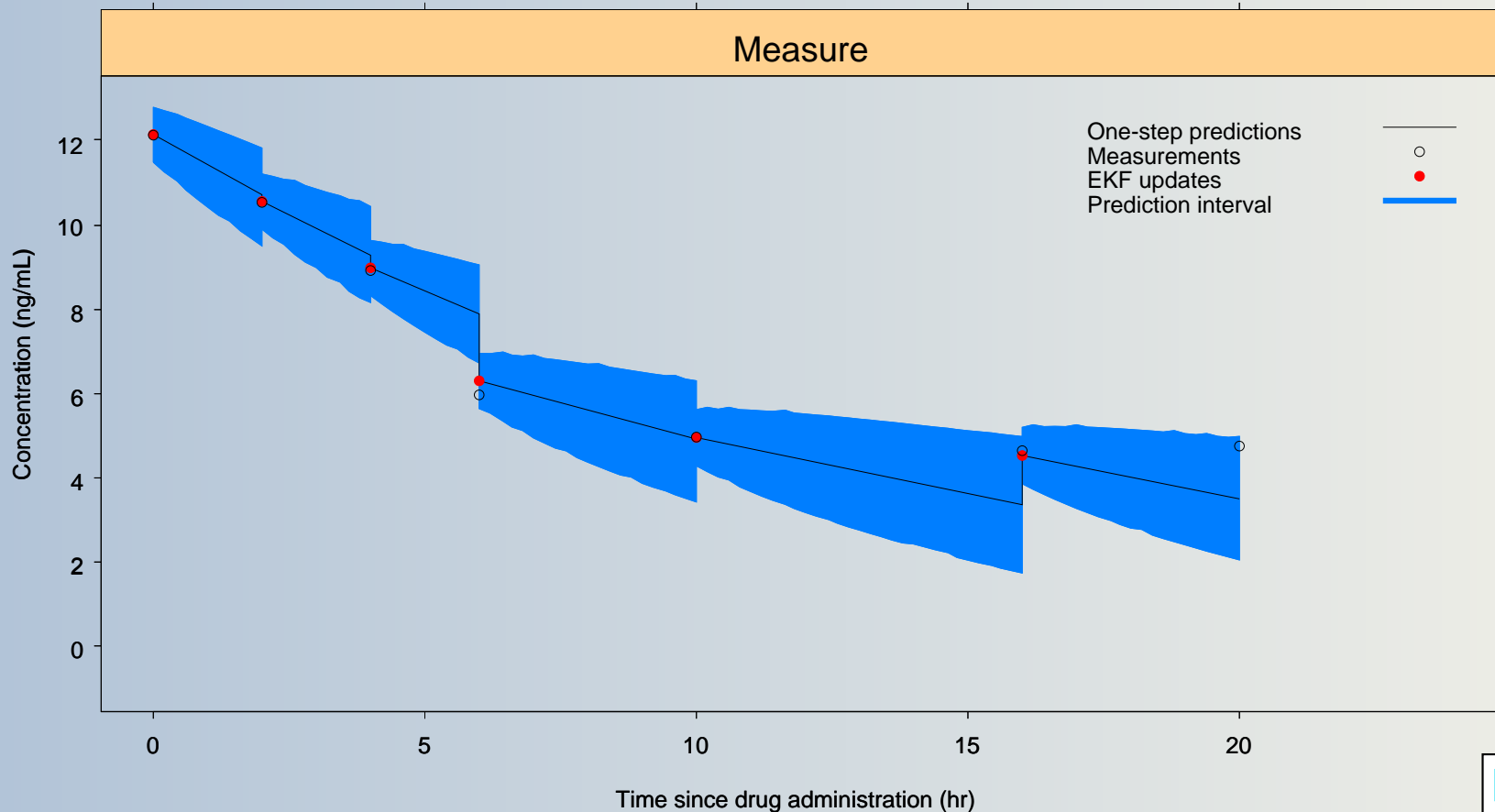
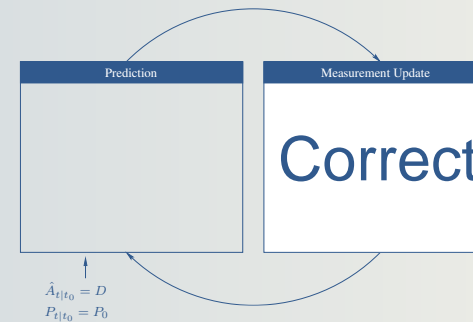
# Methods

## Extended Kalman Filter



# Methods

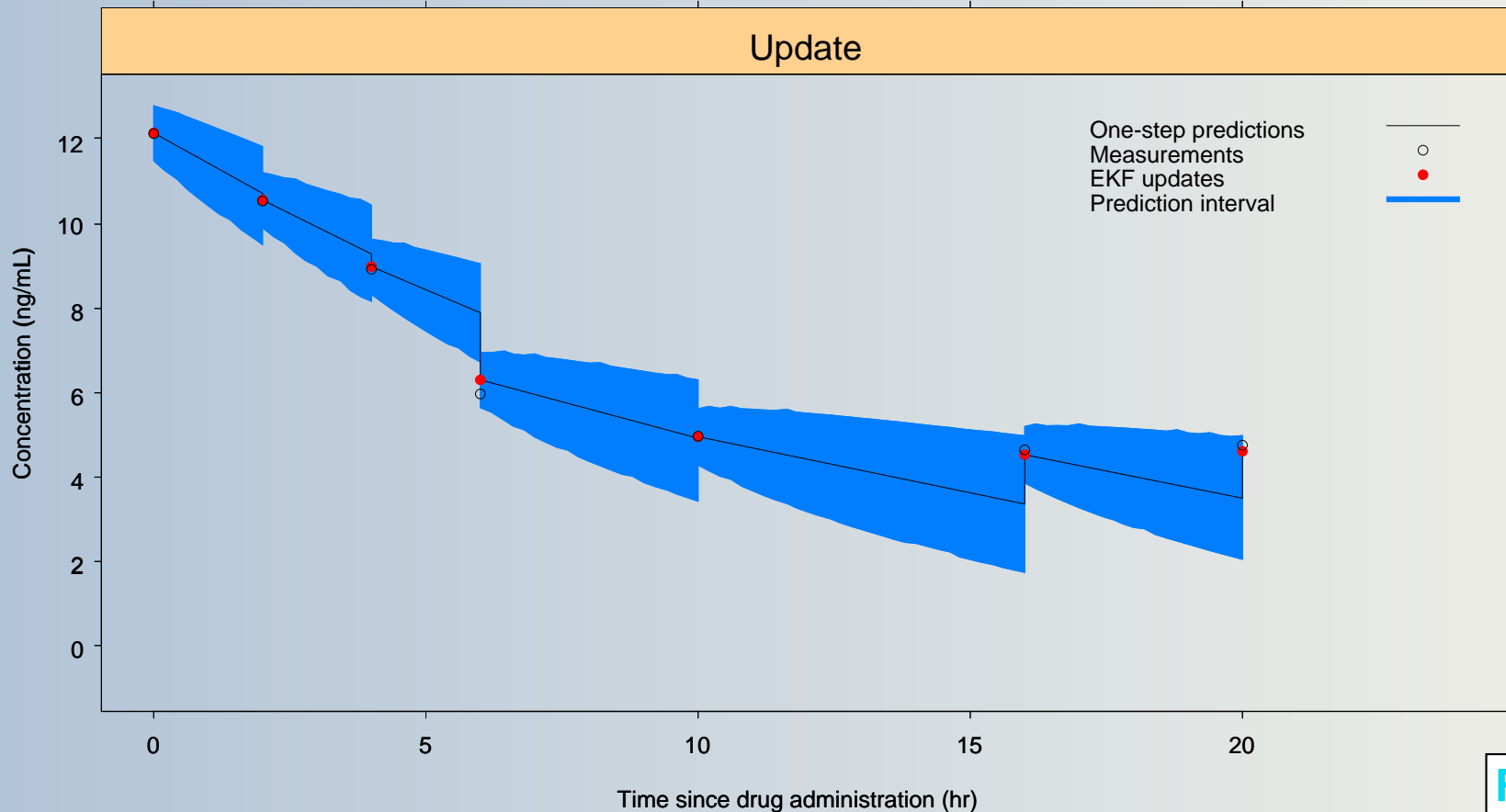
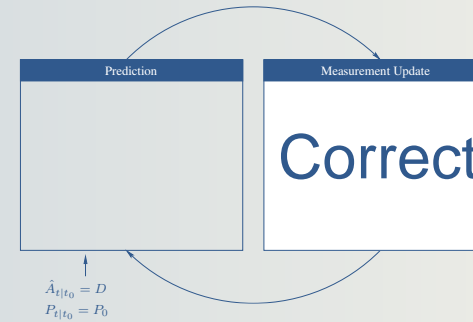
## Extended Kalman Filter





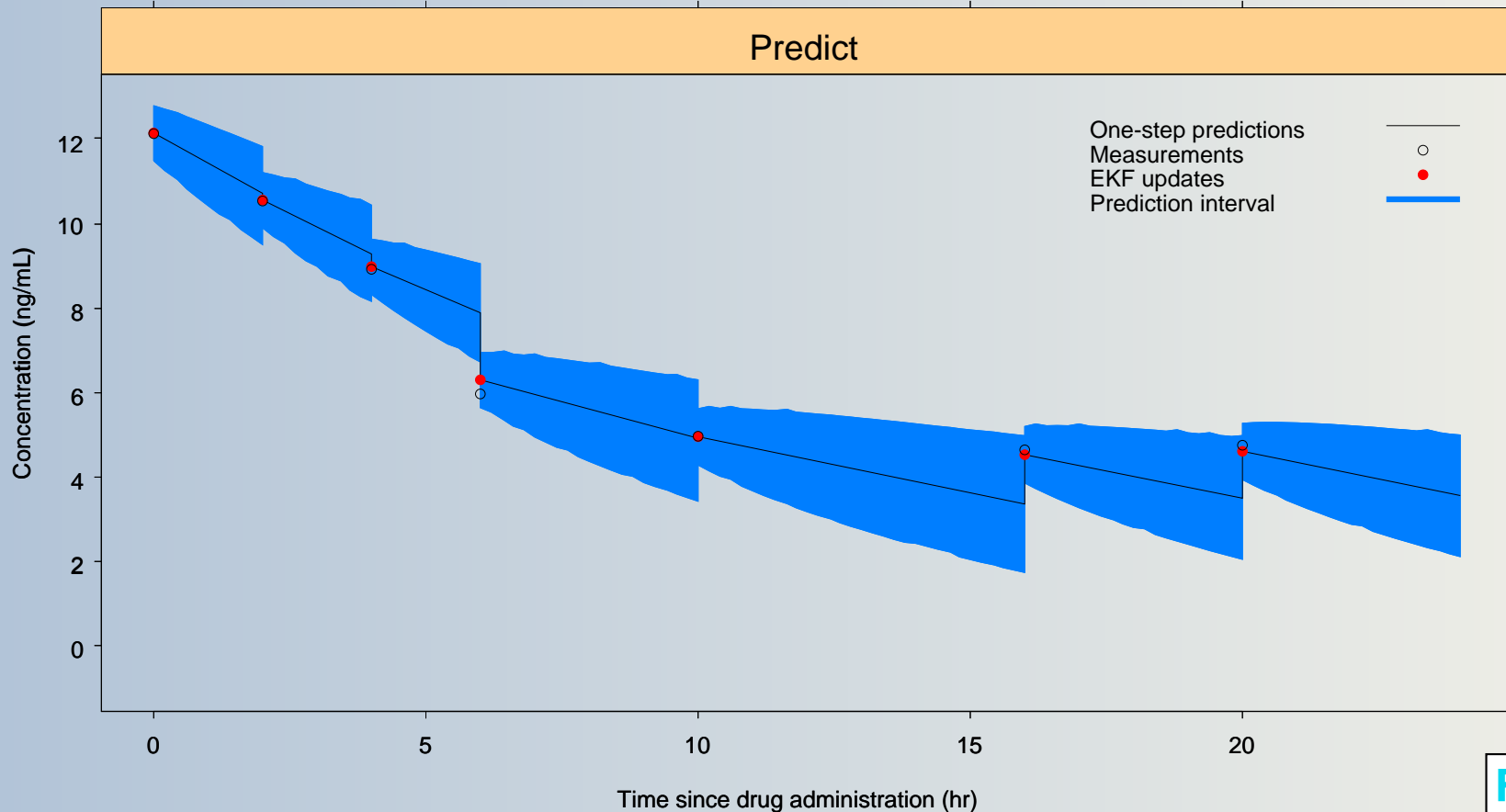
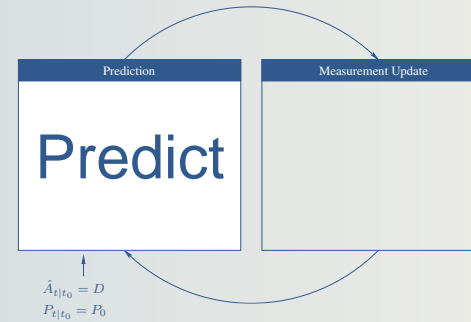
# Methods

## Extended Kalman Filter



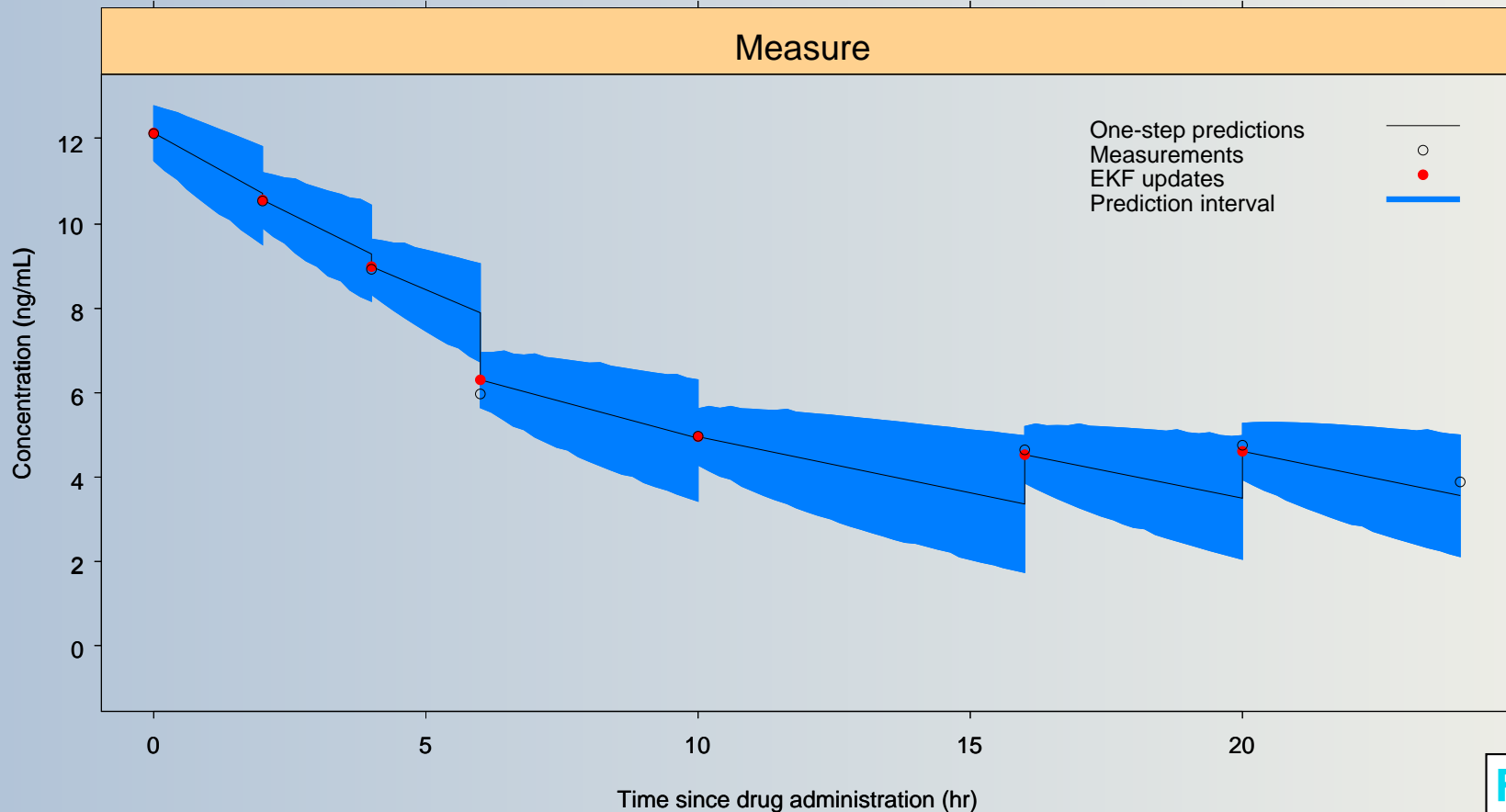
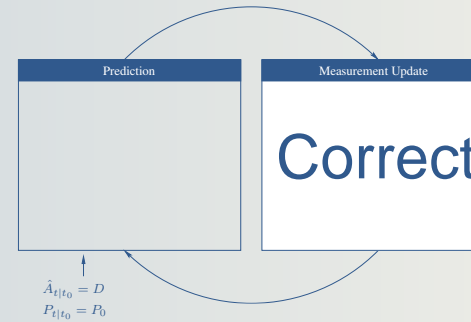
# Methods

## Extended Kalman Filter



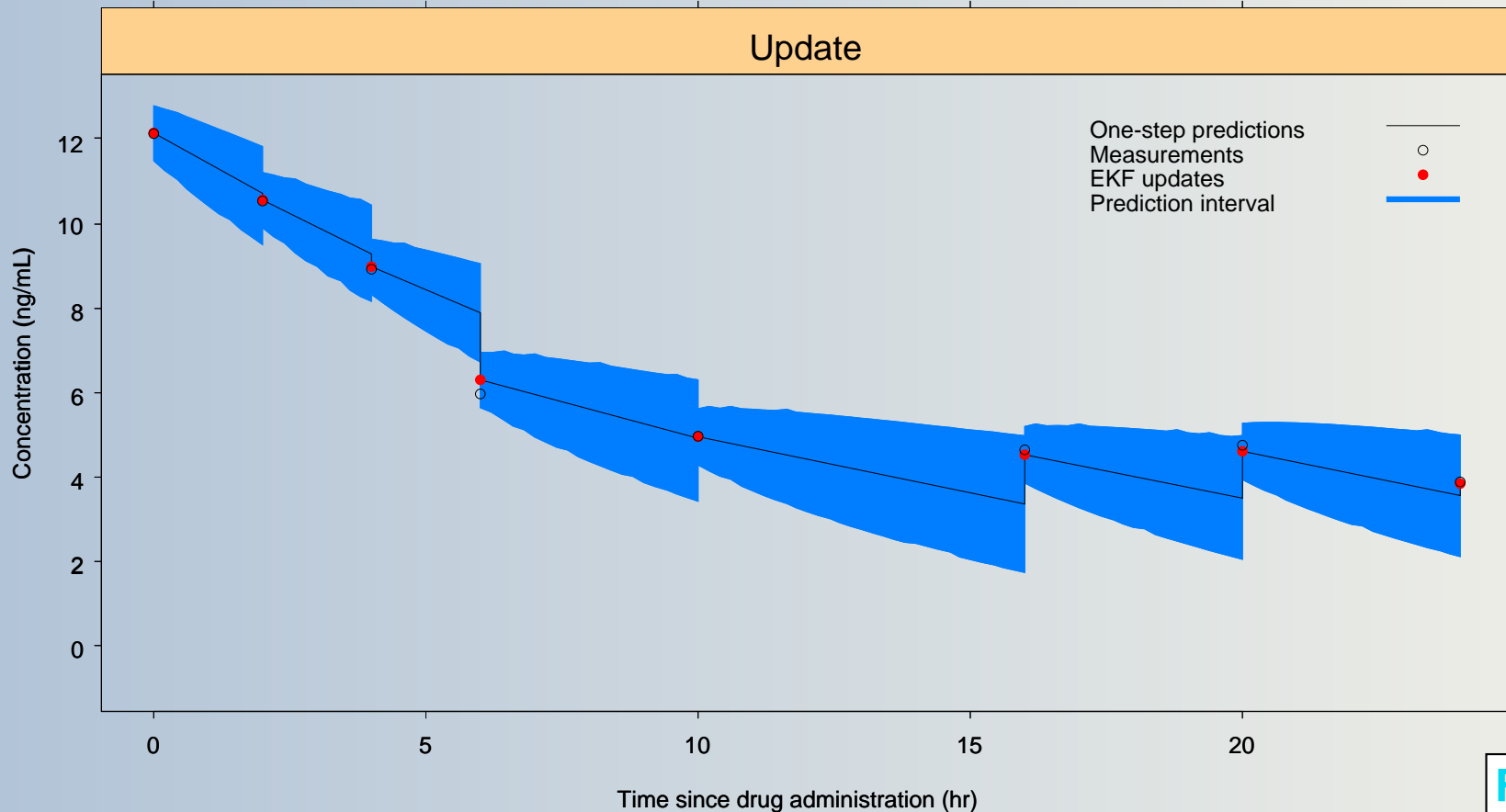
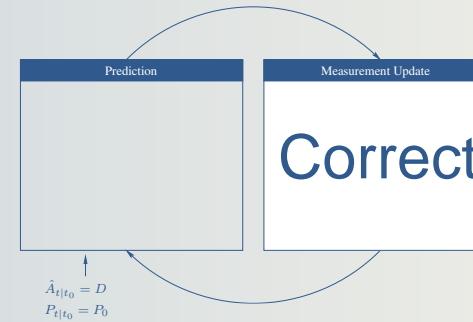
# Methods

## Extended Kalman Filter



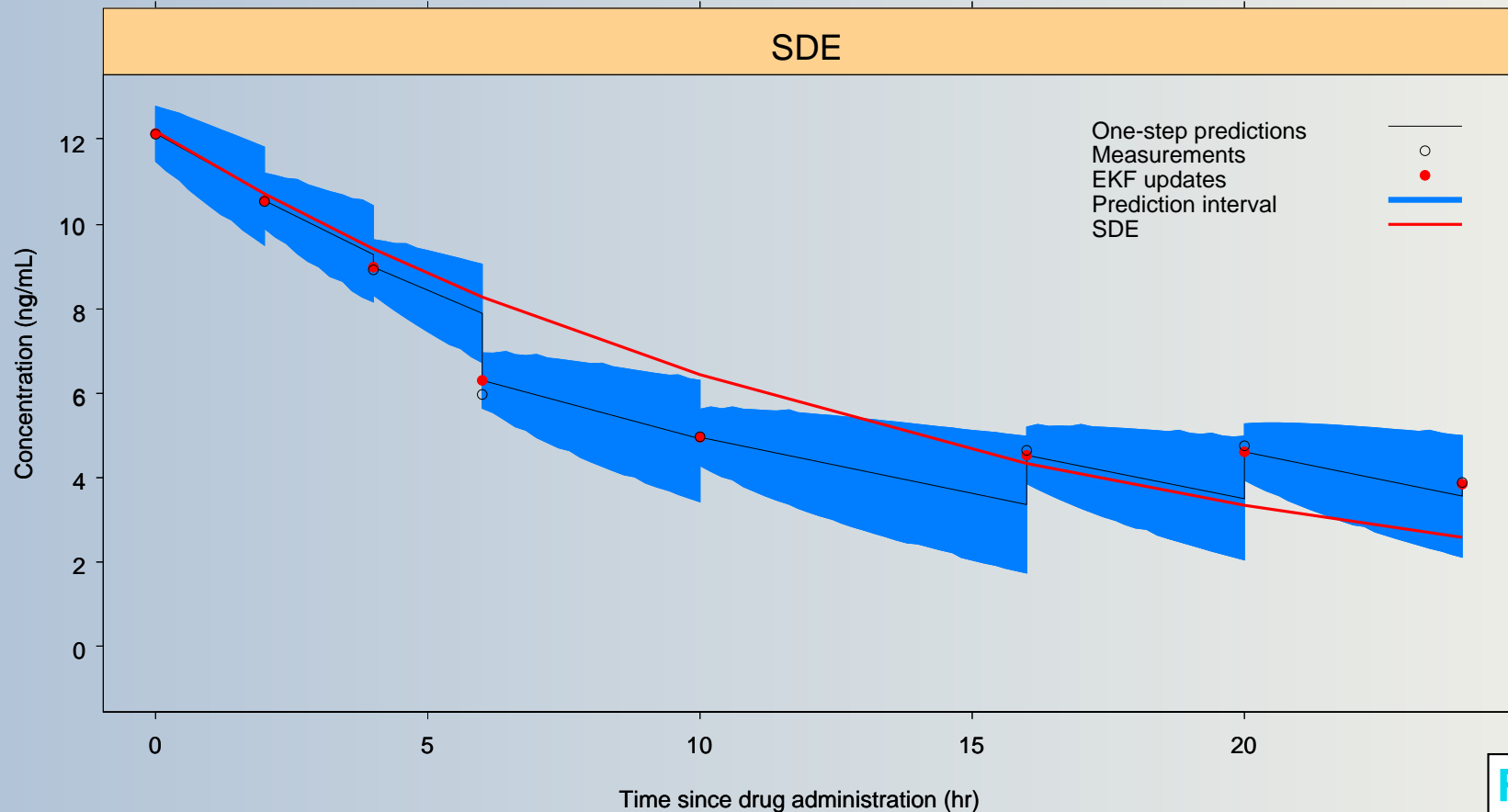
# Methods

## Extended Kalman Filter



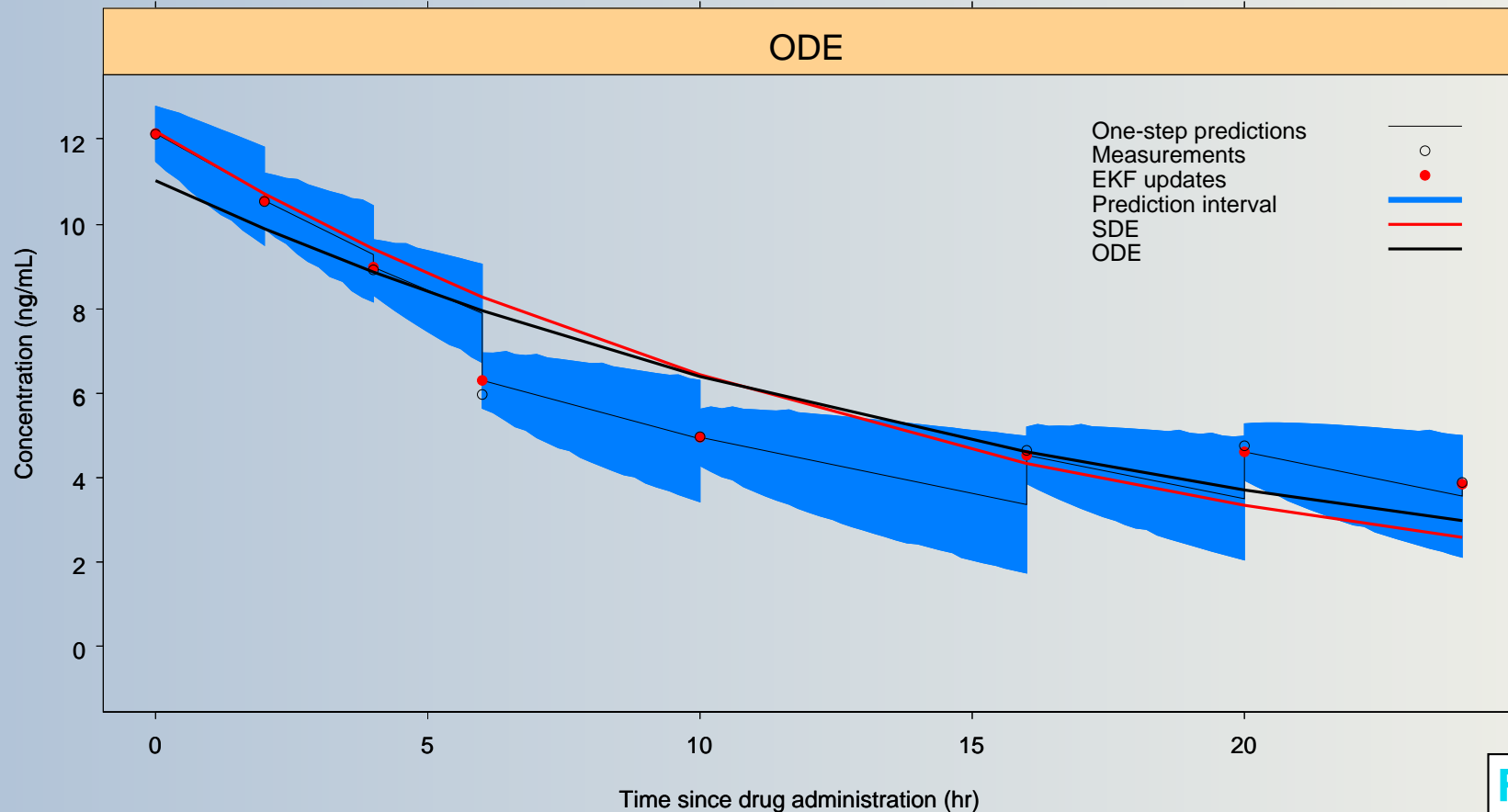
# Methods

## Extended Kalman Filter



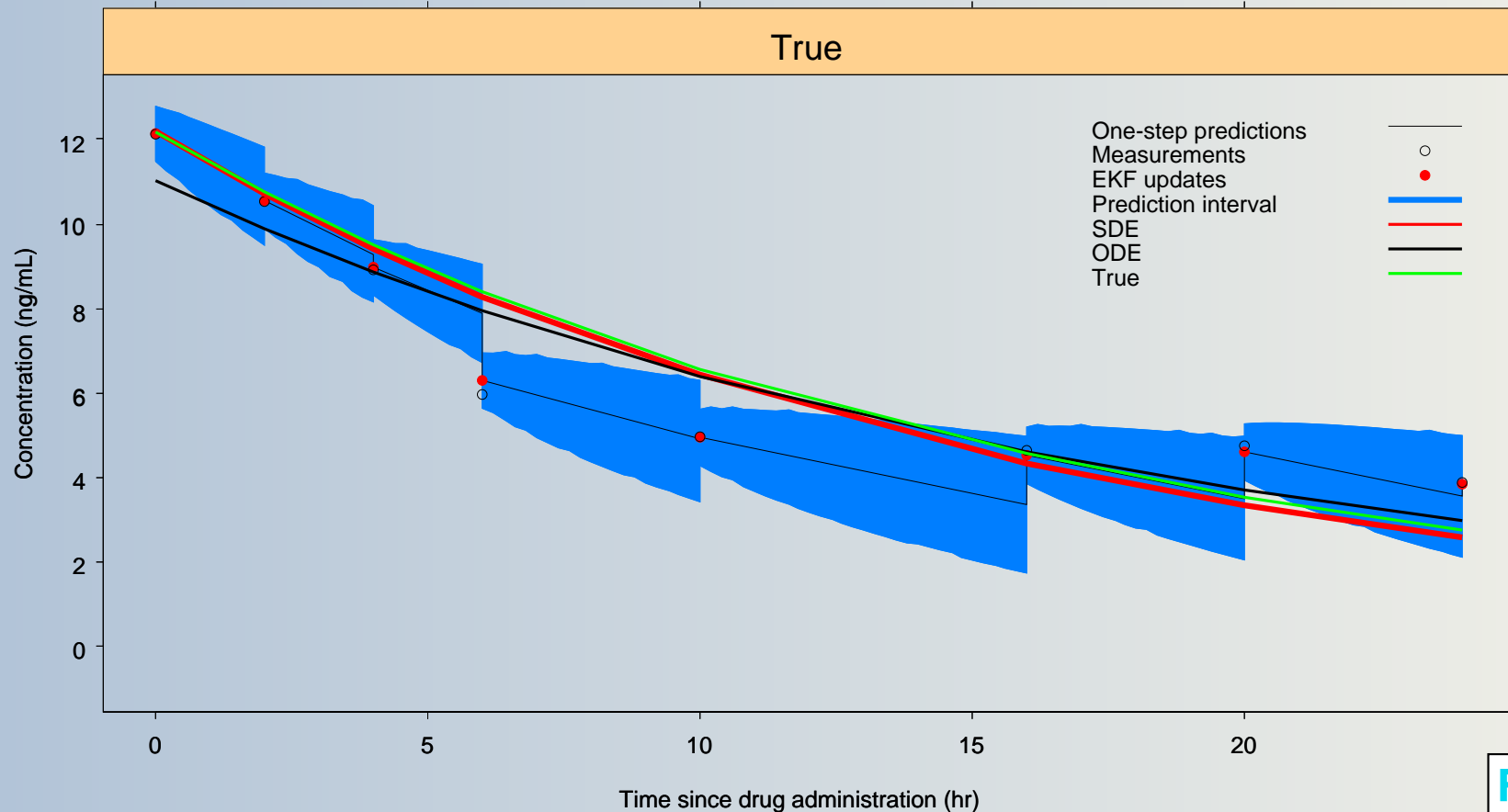
# Methods

## Extended Kalman Filter



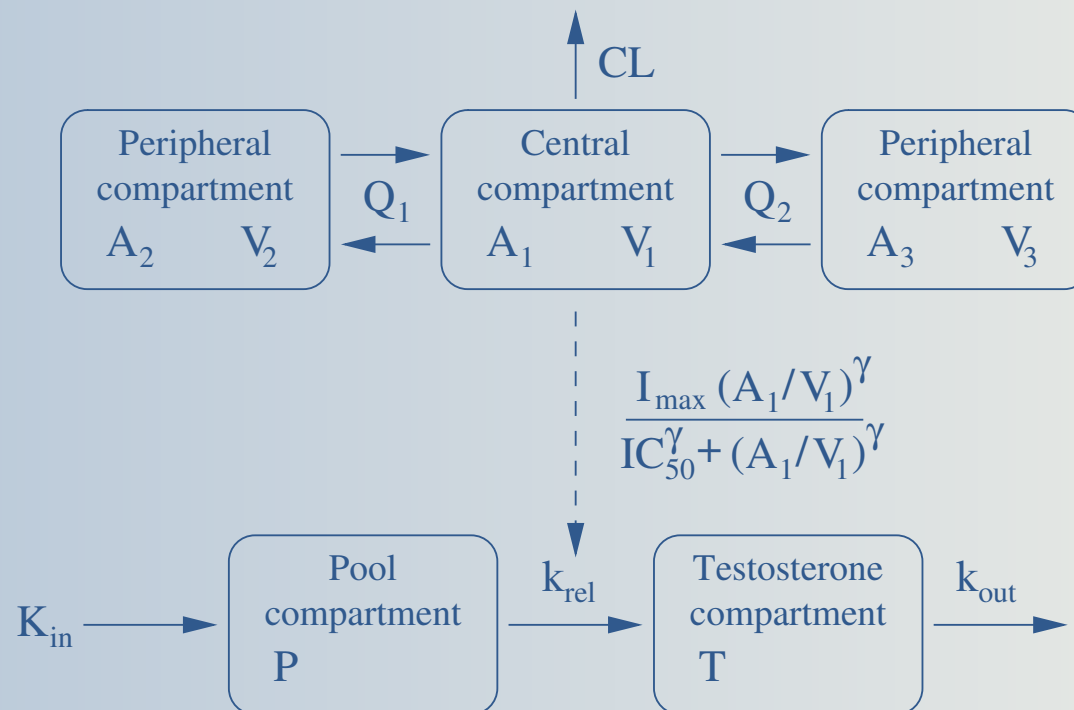
# Methods

## Extended Kalman Filter



# Results

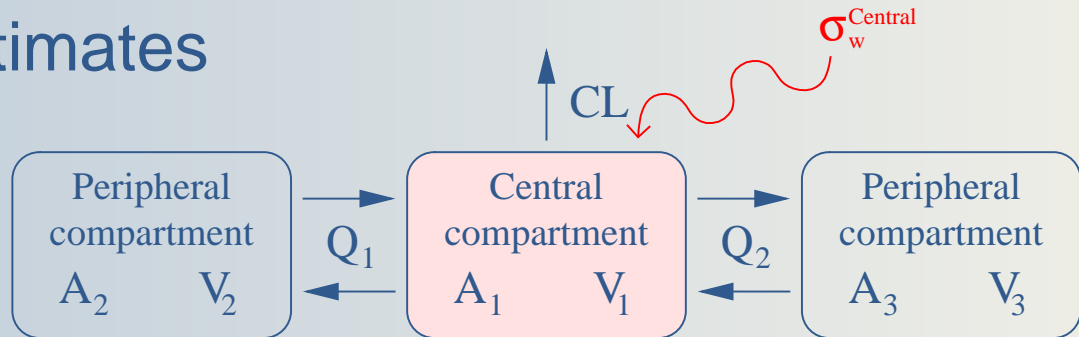
- PK/PD modelling of GnRH antagonist degarelix
  - Degarelix IV infusion phase I study with 24 subjects
  - Sequential PK/PD data analysis
  - FOCE method with INTERACTION





# Results

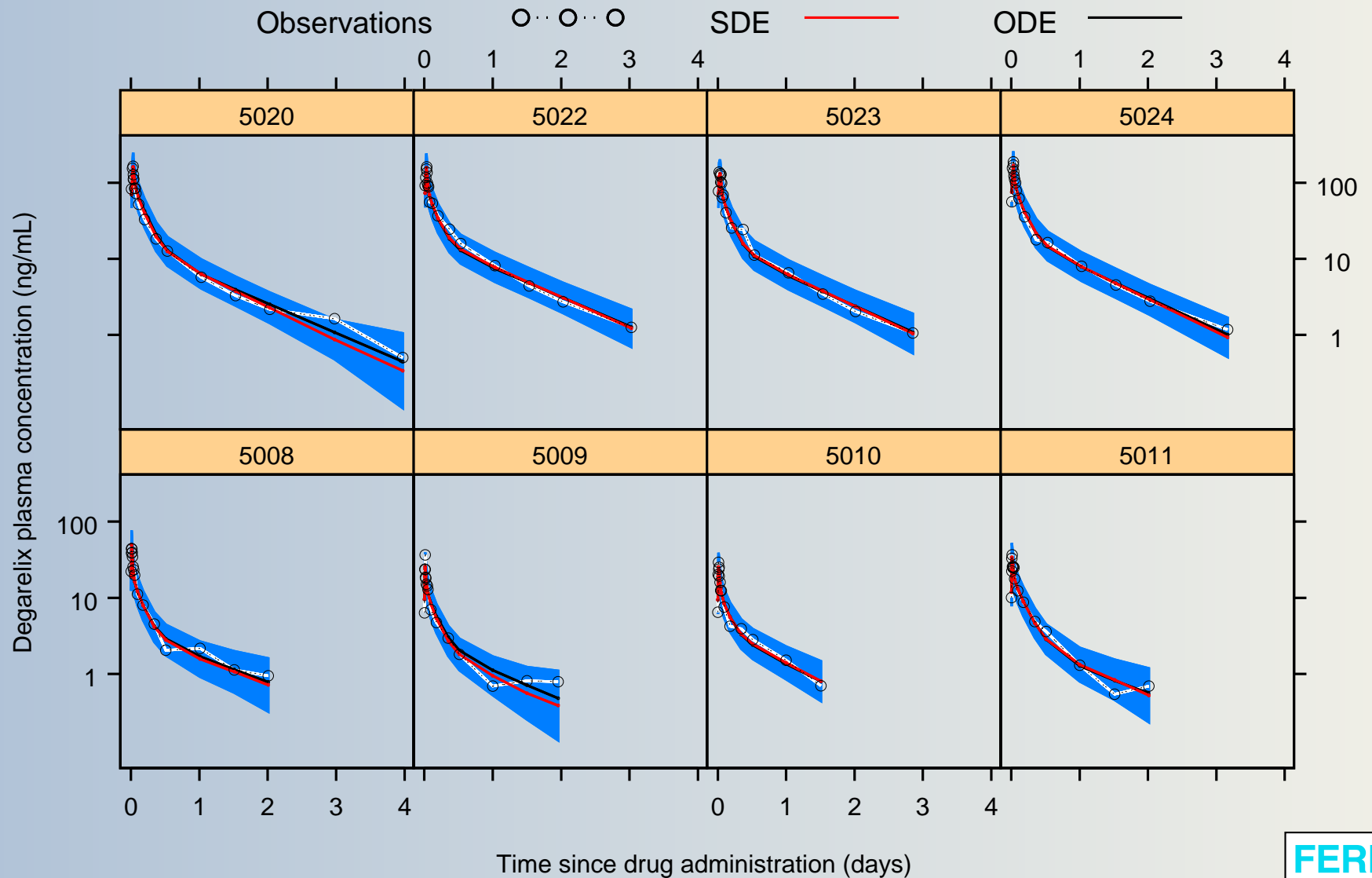
## PK parameter estimates



Parameter	ODE	SDE	Relative diff.
OFV	-714	-721	
CL	3.29	3.32	0%
Q <sub>1</sub>	2.57	2.63	2%
Q <sub>2</sub>	10.7	11.0	3%
V <sub>1</sub>	9.78	9.69	1%
V <sub>2</sub>	31.7	30.4	4%
V <sub>3</sub>	8.87	8.70	2%
IIV CL	17.6	17.6	0%
IIV Q <sub>1</sub>	30.8	32.7	6%
IIV V <sub>1</sub>	27.7	27.8	0%
$\sigma$	19.8	18.8	5%
$\sigma_w^{\text{Central}}$		2.08	

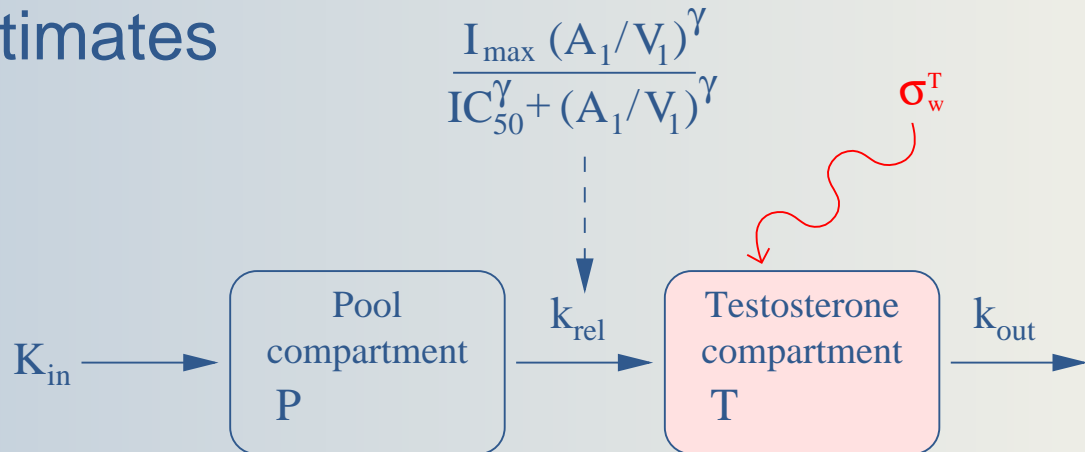
# Results

## ● PK concentration-time profiles



# Results

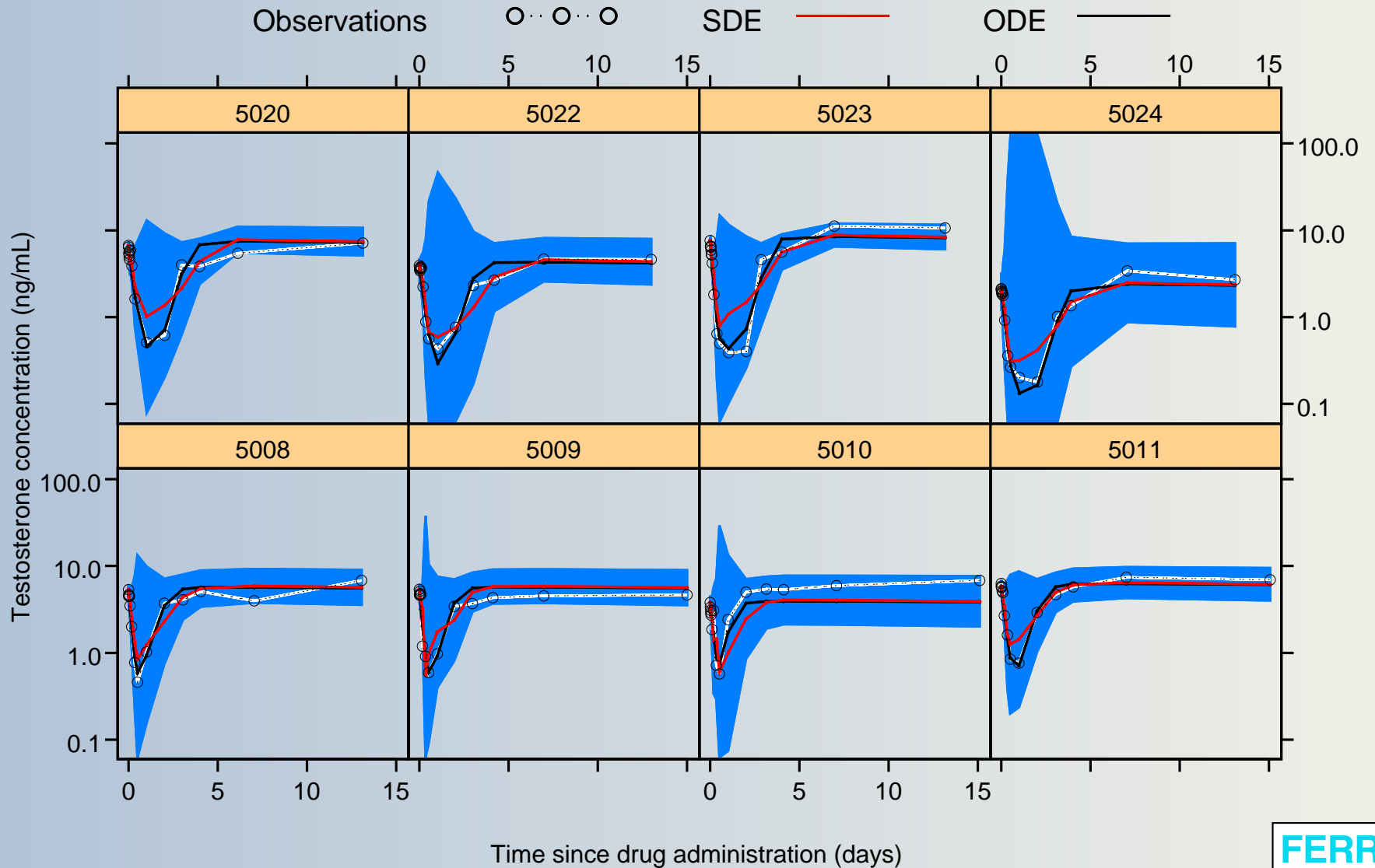
## ● PD parameter estimates



Parameter	ODE	SDE	Relative diff.
OFV	-565	-643	
$k_{out}$	0.22	0.21	3%
$k_{rel}$	0.0024	0.0035	46%
$I_{\max}$	0.95	0.87	9%
$IC_{50}$	0.59	0.40	33%
$\gamma$	3.00	1.68	44%
IIV $k_{out}$	18.7	5.93	68%
IIV $IC_{50}$	54.6	32.6	40%
$\sigma$	23.9	3.69	85%
$\sigma_w^T$		0.726	

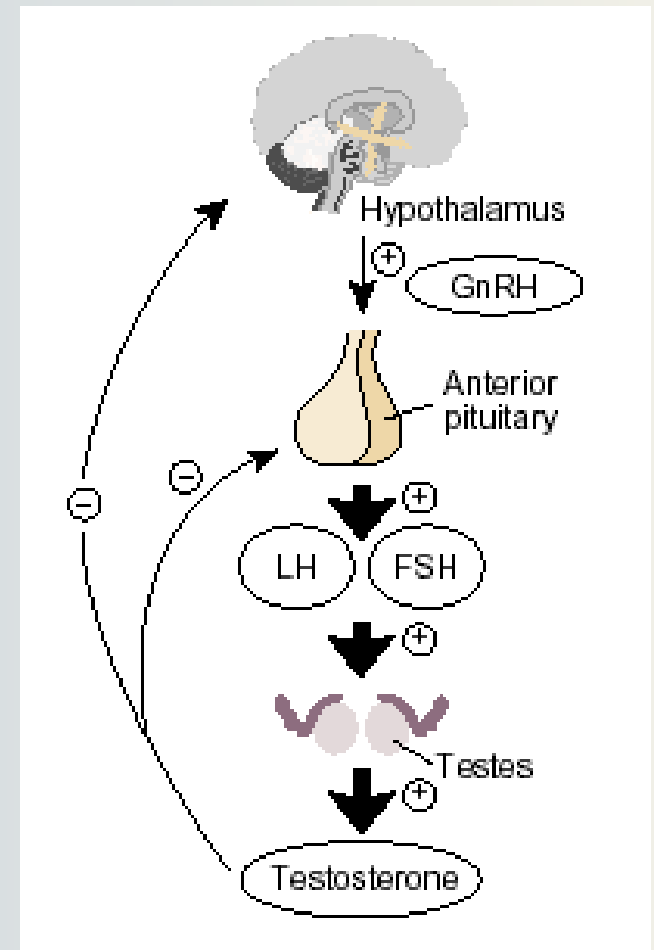
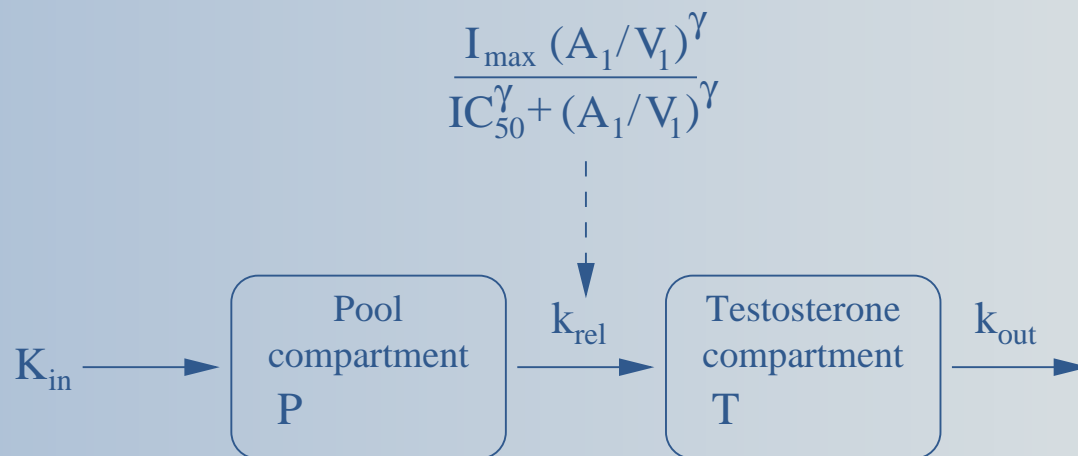
# Results

## ● PD concentration-time profiles



# Results

- Pinpoint PD model deficiencies
  - Hypothalamic-Pituitary-Gonadal (HPG) axis
    - Variations in testosterone production
    - HPG mechanisms of action

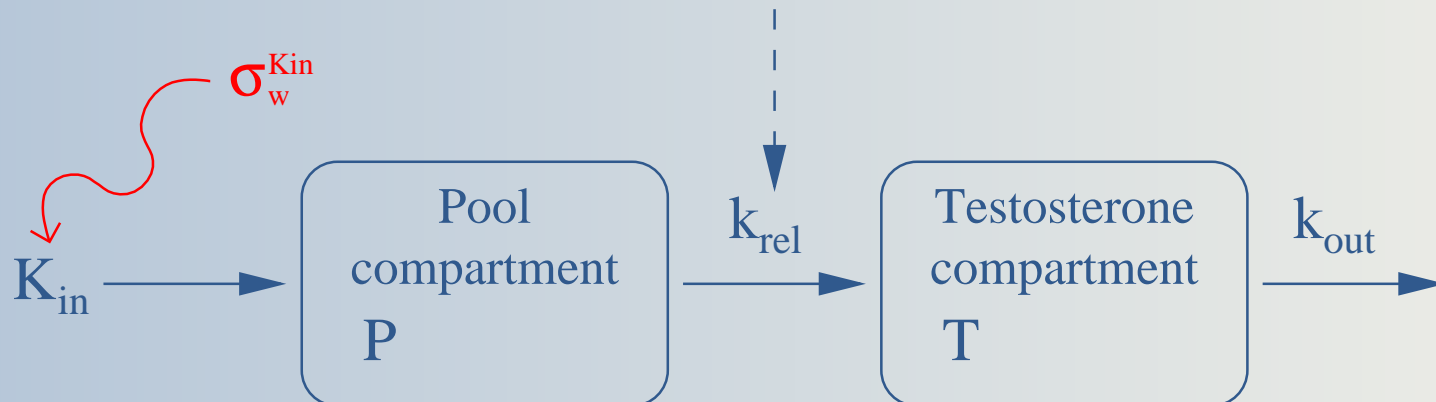


# Results

- Pinpoint PD model deficiencies
  - Variations in testosterone production

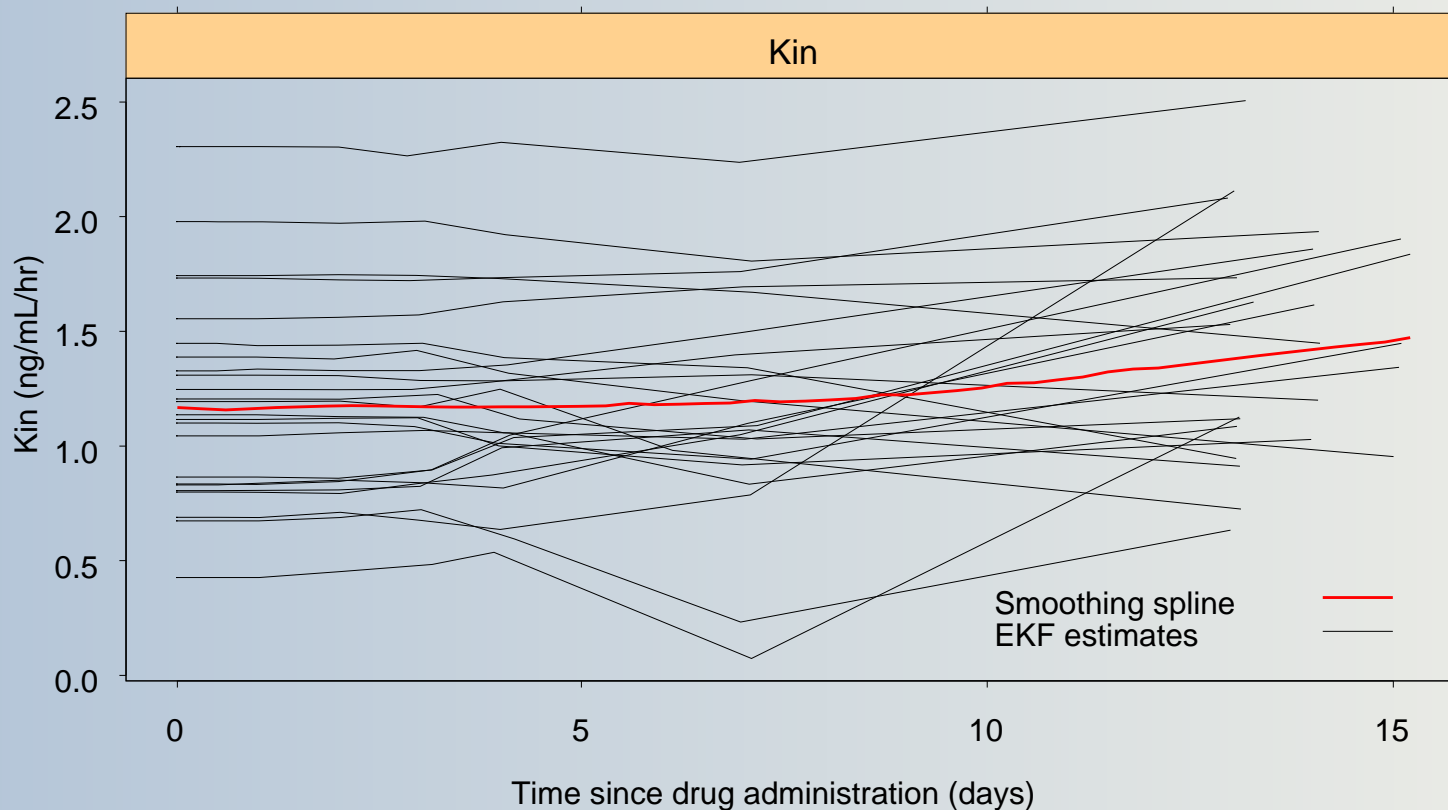
$$\begin{pmatrix} dP \\ dT \\ dK_{in} \end{pmatrix} = \begin{pmatrix} K_{in} - k_{rel} \left( 1 - \frac{I_{max} C_p^\gamma}{IC_{50}^\gamma + C_p^\gamma} \right) P \\ k_{rel} \left( 1 - \frac{I_{max} C_p^\gamma}{IC_{50}^\gamma + C_p^\gamma} \right) P - k_{out} T \\ 0 \end{pmatrix} dt + \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \sigma_w^{Kin} \end{pmatrix} d\mathbf{w}_t$$

$$\frac{I_{max} (A_1/V_1)^\gamma}{IC_{50}^\gamma + (A_1/V_1)^\gamma}$$



# Results

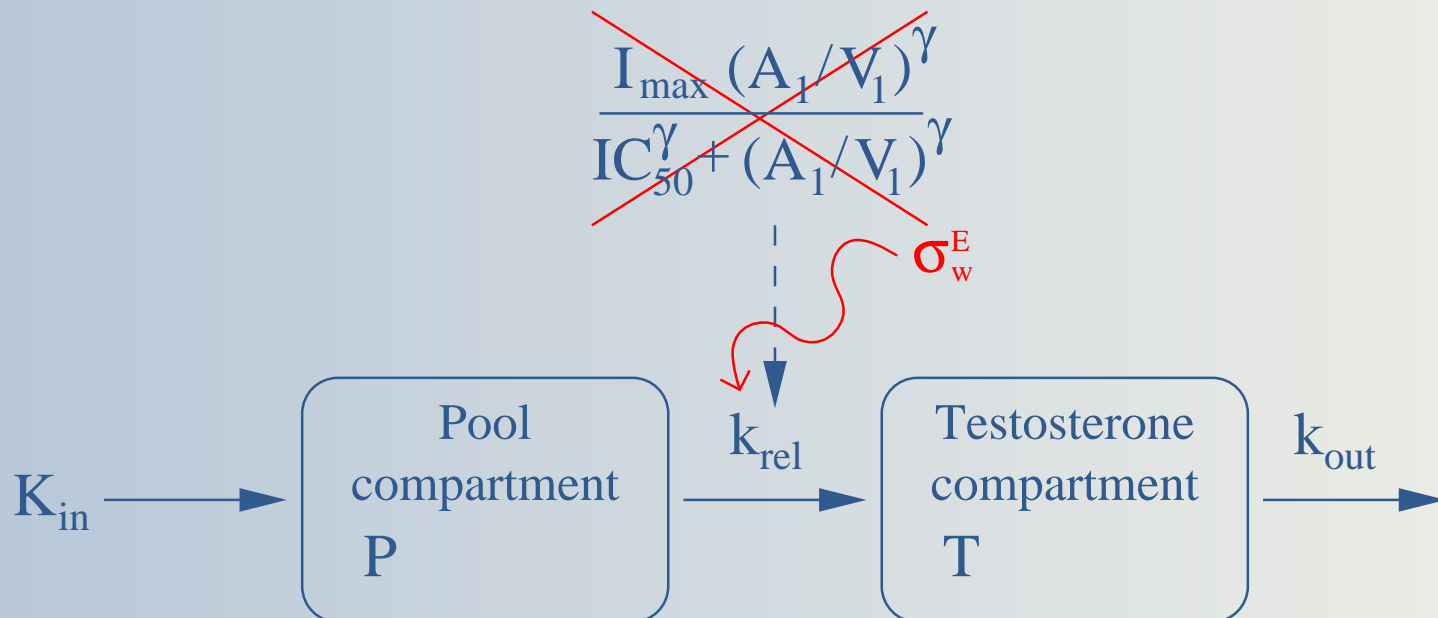
- Pinpoint PD model deficiencies
- Variations in testosterone production



# Results

- Pinpoint PD model deficiencies
  - HPG mechanisms of action

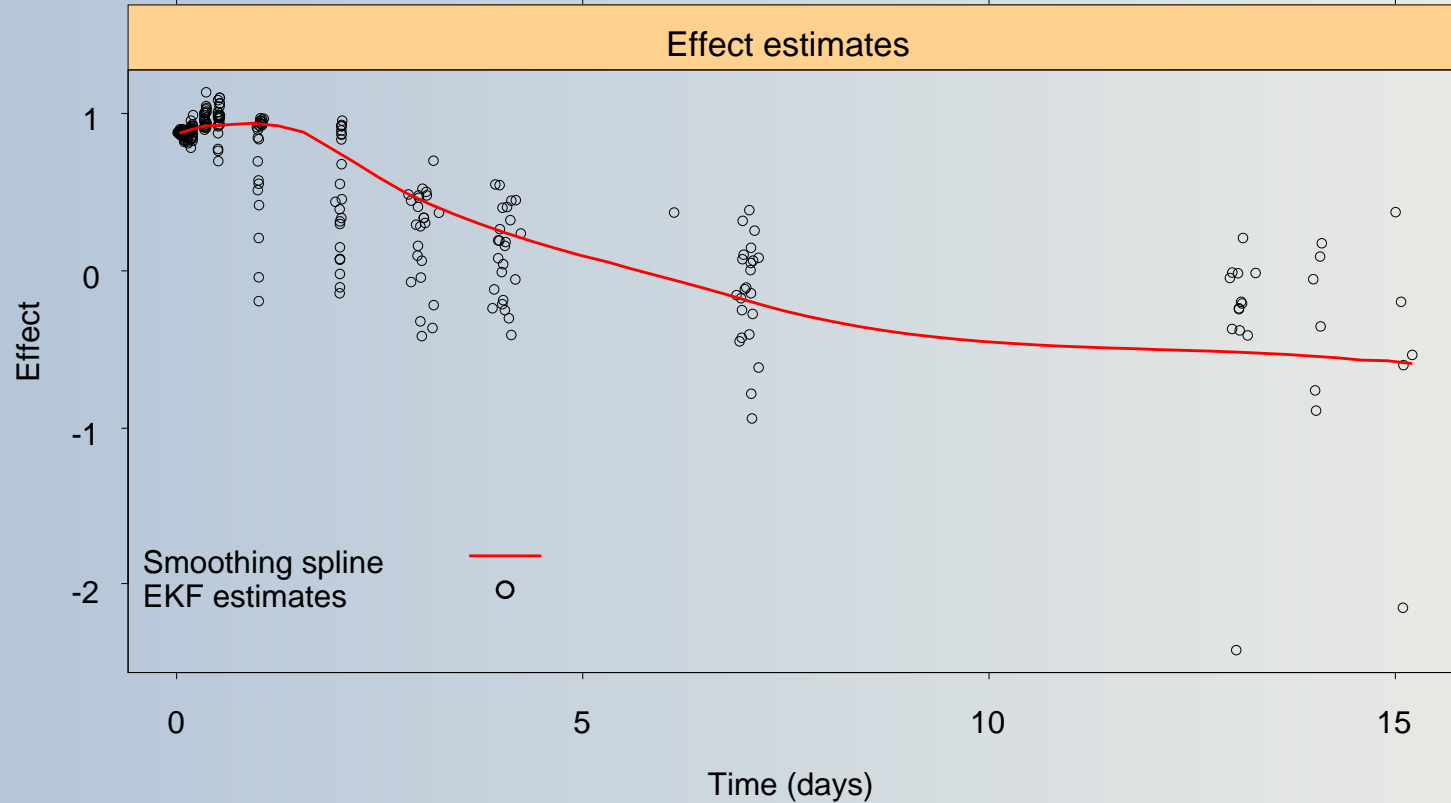
$$\begin{pmatrix} dP \\ dT \\ dE \end{pmatrix} = \begin{pmatrix} K_{in} - k_{rel} (1 - E) P \\ k_{rel} (1 - E) P - k_{out} T \\ 0 \end{pmatrix} dt + \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \sigma_w^E \end{pmatrix} d\mathbf{w}_t$$





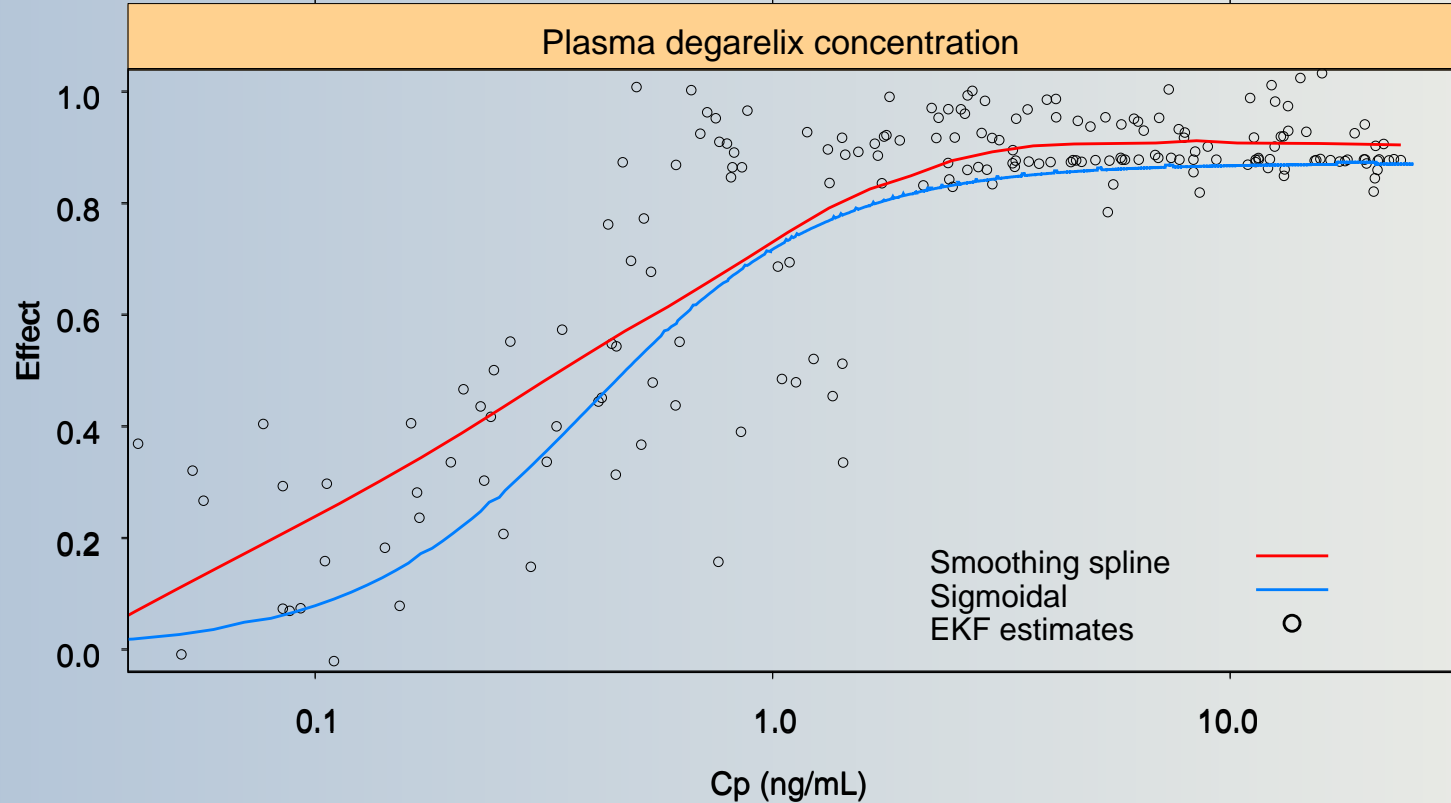
# Results

- Pinpoint PD model deficiencies
- HPG mechanisms of action



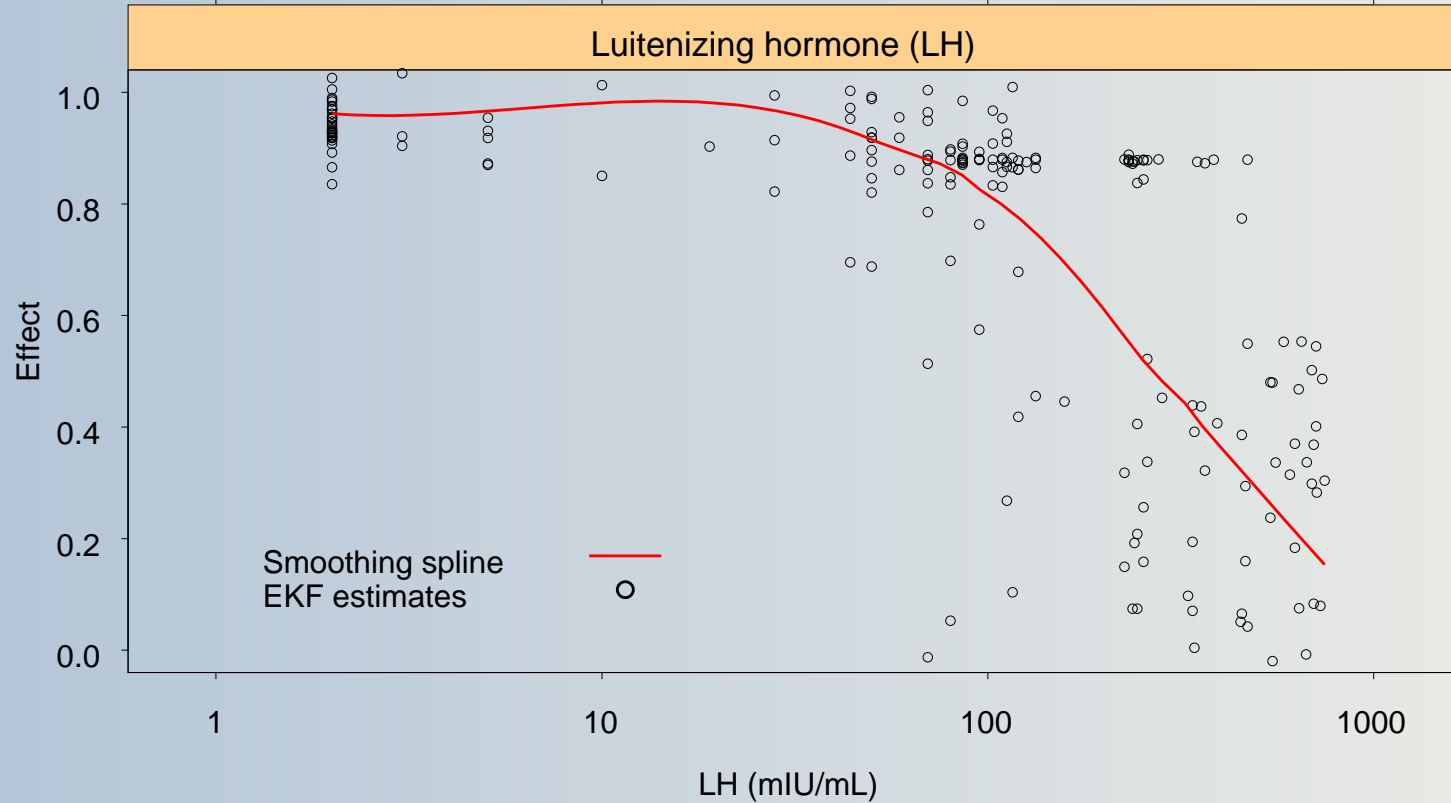
# Results

- Pinpoint PD model deficiencies
- HPG mechanisms of action



# Results

- Pinpoint PD model deficiencies
- HPG mechanisms of action



# Conclusion

- Stochastic differential equations
  - Residual error is decomposed into system and measurement noise.
  - SDE model reduces to ODE model if the system noise is insignificant.
  - Provide a diagnostic tool for pinpointing model deficiencies.

# Conclusion

- PK/PD of GnRH antagonist degarelix
  - Significant system noise parameters in PK/PD model
    - PK: Random physiological fluctuations
    - PD: Model misspecification
  - Pinpoint PD model deficiencies
    - Tracking of  $K_{in}$  parameter
    - Deconvolution of effect model

# Questions ?